Measures of centrality

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Principles of Complex Systems, Vols. 1, 2, & 3D CSYS/MATH 300, 303, & 394, 2022-2023 | @pocsvox

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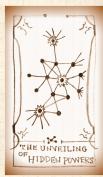
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Basic question: how 'important' are specific nodes and edges in a network?

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

1. handle a relatively large amount of the network's traffic (e.g., cars, information);

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

- 1. handle a relatively large amount of the network's traffic (e.g., cars, information);
- 2. bridge two or more distinct groups (e.g., liason, interpreter);

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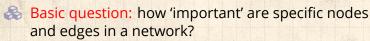
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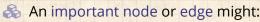
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- 1. handle a relatively large amount of the network's traffic (e.g., cars, information);
- bridge two or more distinct groups (e.g., liason, interpreter);
- 3. be a source of important ideas, knowledge, or judgments (e.g., supreme court decisions, an employee who 'knows where everything is').

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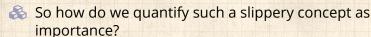


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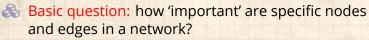
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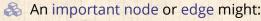
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Nutshell







- 1. handle a relatively large amount of the network's traffic (e.g., cars, information);
- bridge two or more distinct groups (e.g., liason, interpreter);
- 3. be a source of important ideas, knowledge, or judgments (e.g., supreme court decisions, an employee who 'knows where everything is').
- So how do we quantify such a slippery concept as importance?
- We generate ad hoc, reasonable measures, and examine their utility ...

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One possible reflection of importance is centrality.

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One possible reflection of importance is centrality.



Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.

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Idea of centrality comes from social networks literature [7]

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One possible reflection of importance is centrality.

Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.

Idea of centrality comes from social networks literature [7].

Many flavors of centrality ...

- 1. Many are topological and quasi-dynamical;
- 2. Some are based on dynamics (e.g., traffic).

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- One possible reflection of importance is centrality.
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- Many flavors of centrality ...
 - 1. Many are topological and quasi-dynamical;
 - 2. Some are based on dynamics (e.g., traffic).
- We will define and examine a few ...

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🙈 Many flavors of centrality ...

- 1. Many are topological and quasi-dynamical;
- 2. Some are based on dynamics (e.g., traffic).
- We will define and examine a few ...

(Later: see centrality useful in identifying communities in networks.)

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Degree centrality

Naively estimate importance by node degree. [7]

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Degree centrality



Naively estimate importance by node degree. [7]



Doh: assumes linearity (If node i has twice as many friends as node j, it's twice as important.)

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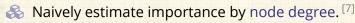
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Degree centrality



Noh: assumes linearity (If node i has twice as many friends as node j, it's twice as important.)

Doh: doesn't take in any non-local information.

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🚵 Idea: Nodes are more central if they can reach other nodes 'easily.'

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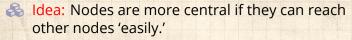
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Measure average shortest path from a node to all other nodes.

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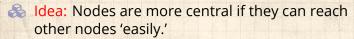
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Nutshell





Measure average shortest path from a node to all other nodes.

Define Closeness Centrality for node i as

 $\frac{N-1}{\sum_{j,j\neq i} (\text{shortest distance from } i \text{ to } j).}$

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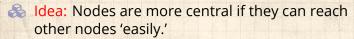
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Range is 0 (no friends) to 1 (single hub).

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Nutshell



- Idea: Nodes are more central if they can reach other nodes 'easily.'
- Measure average shortest path from a node to all other nodes.
- & Define Closeness Centrality for node i as

$$\frac{N-1}{\sum_{j,\,j\neq i}(\text{shortest distance from }i\text{ to }j)}.$$

- Range is 0 (no friends) to 1 (single hub).
- Unclear what the exact values of this measure tells us because of its ad-hocness.

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- General problem with simple centrality measures: what do they exactly mean?

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- Range is 0 (no friends) to 1 (single hub).
- Unclear what the exact values of this measure tells us because of its ad-hocness.
- General problem with simple centrality measures: what do they exactly mean?
- Perhaps, at least, we obtain an ordering of nodes in terms of 'importance.'

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Betweenness centrality is based on coherence of shortest paths in a network.

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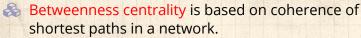
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Idea: If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion. The PoCSverse Measures of centrality 13 of 33

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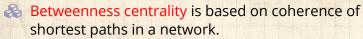
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Nutshell





Idea: If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion.

For each node *i*, count how many shortest paths pass through *i*.

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In the case of ties, divide counts between paths.

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& Call frequency of shortest paths passing through node i the betweenness of i, B_i .

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& Note: Exclude shortest paths between i and other nodes.

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Note: works for weighted and unweighted networks.

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(possibly weighted).

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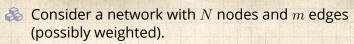
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 \bigotimes Computational goal: Find $\binom{N}{2}$ shortest paths \square between all pairs of nodes.

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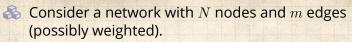
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Traditionally use Floyd-Warshall
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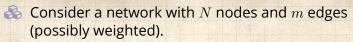
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 \bigotimes Computational goal: Find $\binom{N}{2}$ shortest paths \square between all pairs of nodes.

& Computation time grows as $O(N^3)$.

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- $\red{solution}$ Consider a network with N nodes and m edges (possibly weighted).
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 algorithm.
- $\red {\Bbb S}$ Computation time grows as $O(N^3)$.
- 🙈 See also:
 - 1. Dijkstra's algorithm of for finding shortest path between two specific nodes,

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- See also:
 - Dijkstra's algorithm of for finding shortest path between two specific nodes,
 - 2. and Johnson's algorithm \square which outperforms Floyd-Warshall for sparse networks: $O(mN + N^2 \log N)$.

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Newman (2001)^[4, 5] and Brandes (2001)^[1] independently derive equally fast algorithms that also compute betweenness.

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Computation times grow as:

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Computation times grow as:

1. O(mN) for unweighted graphs;

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Newman (2001)^[4, 5] and Brandes (2001)^[1] independently derive equally fast algorithms that also compute betweenness.

Computation times grow as:

1. O(mN) for unweighted graphs;

2. and $O(mN + N^2 \log N)$ for weighted graphs.

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Consider unweighted networks.

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Consider unweighted networks.



Use breadth-first search:

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Consider unweighted networks.

- Use breadth-first search:
 - 1. Start at node i, giving it a distance d = 0 from itself.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d = 1.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d = 1.
- 3. Go through list of most recently visited nodes and find all of their neighbors.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d = 1.
- 3. Go through list of most recently visited nodes and find all of their neighbors.
- 4. Exclude any nodes already assigned a distance.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d = 1.
- 3. Go through list of most recently visited nodes and find all of their neighbors.
- 4. Exclude any nodes already assigned a distance.
- 5. Increment distance d by 1.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
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- 3. Go through list of most recently visited nodes and find all of their neighbors.
- 4. Exclude any nodes already assigned a distance.
- 5. Increment distance d by 1.
- 6. Label newly reached nodes as being at distance d.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d = 1.
- 3. Go through list of most recently visited nodes and find all of their neighbors.
- 4. Exclude any nodes already assigned a distance.
- 5. Increment distance d by 1.
- 6. Label newly reached nodes as being at distance d.
- 7. Repeat steps 3 through 6 until all nodes are visited.

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Nutshell





Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d = 1.
- 3. Go through list of most recently visited nodes and find all of their neighbors.
- 4. Exclude any nodes already assigned a distance.
- 5. Increment distance d by 1.
- 6. Label newly reached nodes as being at distance d.
- 7. Repeat steps 3 through 6 until all nodes are visited.



Record which nodes link to which nodes moving out from *i* (former are 'predecessors' with respect to *i*'s shortest path structure).

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Runs in O(m) time and gives N-1 shortest paths.

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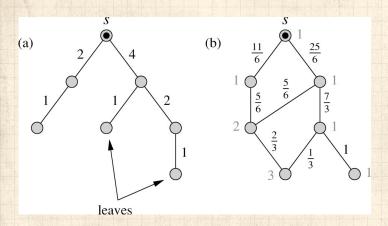
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1. Set all nodes to have a value $c_{ij}=0,\,j=1,...$ (c for count).

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Nutshell



- 1. Set all nodes to have a value $c_{ij}=0$, $j=1,\dots$ (c for count).
- 2. Select one node i and find shortest paths to all other N-1 nodes using breadth-first search.

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- 1. Set all nodes to have a value $c_{ij}=0,\,j=1,...$ (c for count).
- 2. Select one node i and find shortest paths to all other N-1 nodes using breadth-first search.
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- 2. Select one node i and find shortest paths to all other N-1 nodes using breadth-first search.
- 3. Record # equal shortest paths reaching each node.
- 4. Move through nodes according to their distance from *i*, starting with the furthest.

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- 1. Set all nodes to have a value $c_{ij}=$ 0, j=1,... (c for count).
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- 3. Record # equal shortest paths reaching each node.
- 4. Move through nodes according to their distance from i, starting with the furthest.
- 5. Travel back towards i from each starting node j, along shortest path(s), adding 1 to every value of $c_{i\ell}$ at each node ℓ along the way.

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- 6. Whenever more than one possibility exists, apportion according to total number of short paths coming through predecessors.

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- 7. Exclude starting node j and i from increment.

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- 1. Set all nodes to have a value $c_{ij}=0,\,j=1,...$ (c for count).
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- 5. Travel back towards i from each starting node j, along shortest path(s), adding 1 to every value of $c_{i\ell}$ at each node ℓ along the way.
- 6. Whenever more than one possibility exists, apportion according to total number of short paths coming through predecessors.
- 7. Exclude starting node j and i from increment.
- 8. Repeat steps 2–8 for every node i and obtain betweenness as $B_i = \sum_{i=1}^{N} c_{ij}$.

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 \clubsuit For a pure tree network, c_{ij} is the number of nodes beyond *j* from *i*'s vantage point.

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For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.

Same algorithm for computing drainage area in river networks (with 1 added across the board). The PoCSverse Measures of centrality 18 of 33

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Nutshell



For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.

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For edge betweenness, use exact same algorithm but now

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- For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.
- Same algorithm for computing drainage area in river networks (with 1 added across the board).
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For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.

Same algorithm for computing drainage area in river networks (with 1 added across the board).

For edge betweenness, use exact same algorithm but now

- 1. j indexes edges,
- 2. and we add one to each edge as we traverse it.

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For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.

Same algorithm for computing drainage area in river networks (with 1 added across the board).

For edge betweenness, use exact same algorithm but now

- 1. j indexes edges,
- 2. and we add one to each edge as we traverse it.
- For both algorithms, computation time grows as

O(mN).

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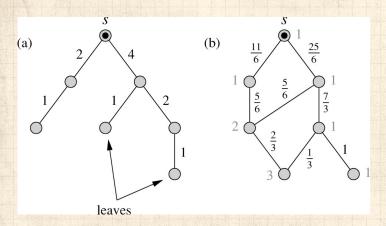
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 \triangle Define x_i as the 'importance' of node i.

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Nutshell





Define x_i as the 'importance' of node i.



 \mathbb{A} Idea: x_i depends (somehow) on x_i if i is a neighbor of i.

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Nutshell





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Recursive: importance is transmitted through a network.

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Define x_i as the 'importance' of node i.

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Simplest possibility is a linear combination:

$$x_i \propto \sum_j a_{ji} x_j$$

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Assume further that constant of proportionality, c, is independent of i.

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- Note: Lots of despair over size of the largest eigenvalue. [7]

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- Eigenvalue equation based on adjacency matrix ...
- Note: Lots of despair over size of the largest eigenvalue. [7] Lose sight of original assumption's non-physicality.

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

But which eigenvalue and eigenvector?

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

But which eigenvalue and eigenvector?

We, the people, would like:

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

But which eigenvalue and eigenvector?

We, the people, would like:

1. A unique solution.

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



But which eigenvalue and eigenvector?



We, the people, would like:

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



But which eigenvalue and eigenvector?



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- 3. Entries of \vec{x} to be real.

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



But which eigenvalue and eigenvector?



We, the people, would like:

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- 4. Entries of \vec{x} to be non-negative.

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- 3. Entries of \vec{x} to be real.
- 4. Entries of \vec{x} to be non-negative.
- 5. λ to actually mean something ...

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- 6. Values of x_i to mean something (what does an observation that $x_3 = 5x_7$ mean?) (maybe only ordering is informative ...)

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



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- 6. Values of x_i to mean something (what does an observation that $x_3 = 5x_7$ mean?) (maybe only ordering is informative ...)

7. λ to equal 1 would be nice ...

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



But which eigenvalue and eigenvector?



We, the people, would like:

- 1. A unique solution.
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- 5. λ to actually mean something ...
- 6. Values of x_i to mean something (what does an observation that $x_3 = 5x_7$ mean?) (maybe only ordering is informative ...)
- 7. λ to equal 1 would be nice ...
- 8. Ordering of \vec{x} entries to be robust to reasonable modifications of linear assumption

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



But which eigenvalue and eigenvector?



We, the people, would like:

- 1. A unique solution.
- 2. λ to be real.
- 3. Entries of \vec{x} to be real.
- 4. Entries of \vec{x} to be non-negative.
- 5. λ to actually mean something ... (maybe too much)
- 6. Values of x_i to mean something (what does an observation that $x_3 = 5x_7$ mean?) (maybe only ordering is informative ...) (maybe too much)
- 7. λ to equal 1 would be nice ... (maybe too much)
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We rummage around in bag of tricks and pull out the Perron-Frobenius theorem ...

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

But which eigenvalue and eigenvector?



We, the people, would like:

- 1. A unique solution. <
- 2. λ to be real. \checkmark
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1. A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for $i=2,\ldots,N$.

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- 1. A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for $i=2,\ldots,N$.
- 2. λ_1 corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.

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- 1. A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for $i=2,\ldots,N$.
- 2. λ_1 corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
- 3. The dominant real eigenvalue λ_1 is bounded by the minimum and maximum row sums of A:

$$\min_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max_i \sum_{j=1}^N a_{ij}$$

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Perron-Frobenius theorem: \square If an $N \times N$ matrix A has non-negative entries then:

- 1. A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for $i=2,\ldots,N$.
- 2. λ_1 corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
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$$\min\nolimits_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max\nolimits_i \sum_{j=1}^N a_{ij}$$

4. All other eigenvectors have one or more negative entries.

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Perron-Frobenius theorem: \square If an $N \times N$ matrix A has non-negative entries then:

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- 3. The dominant real eigenvalue λ_1 is bounded by the minimum and maximum row sums of A:

$$\min\nolimits_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max\nolimits_i \sum_{j=1}^N a_{ij}$$

- 4. All other eigenvectors have one or more negative entries.
- 5. The matrix *A* can make toast.

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Perron-Frobenius theorem: \square If an $N \times N$ matrix A has non-negative entries then:

- 1. A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for $i=2,\ldots,N$.
- 2. λ_1 corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
- 3. The dominant real eigenvalue λ_1 is bounded by the minimum and maximum row sums of A:

$$\min\nolimits_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max\nolimits_i \sum_{j=1}^N a_{ij}$$

- 4. All other eigenvectors have one or more negative entries.
- 5. The matrix *A* can make toast.
- 6. Note: Proof is relatively short for symmetric matrices that are strictly positive [6] and just non-negative [3].

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Assuming our network is irreducible , meaning there is only one component, is reasonable:

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Nutshell



Assuming our network is irreducible , meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.

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Assuming our network is irreducible , meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.

Irreducibility means largest eigenvalue's eigenvector has strictly non-negative entries.

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Nutshell



Assuming our network is irreducible , meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.

Irreducibility means largest eigenvalue's eigenvector has strictly non-negative entries.

Analogous to notion of ergodicity: every state is reachable. The PoCSverse Measures of centrality 24 of 33

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Nutshell



Assuming our network is irreducible , meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.

Irreducibility means largest eigenvalue's eigenvector has strictly non-negative entries.

Analogous to notion of ergodicity: every state is reachable.

(Another term: Primitive graphs and matrices.)

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Generalize eigenvalue centrality to allow nodes to have two attributes:

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Generalize eigenvalue centrality to allow nodes to have two attributes:

> 1. Authority: how much knowledge, information, etc., held by a node on a topic.

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Generalize eigenvalue centrality to allow nodes to have two attributes:

- 1. Authority: how much knowledge, information, etc., held by a node on a topic.
- 2. Hubness (or Hubosity or Hubbishness or Hubtasticness): how well a node 'knows' where to find information on a given topic.

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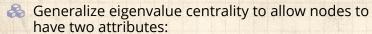
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- 1. Authority: how much knowledge, information, etc., held by a node on a topic.
- 2. Hubness (or Hubosity or Hubbishness or Hubtasticness): how well a node 'knows' where to find information on a given topic.
- Original work due to the legendary Jon Kleinberg. [2]

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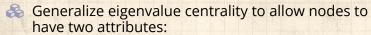
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Nutshell





- 1. Authority: how much knowledge, information, etc., held by a node on a topic.
- 2. Hubness (or Hubosity or Hubbishness or Hubtasticness): how well a node 'knows' where to find information on a given topic.
- Original work due to the legendary Jon Kleinberg. [2]
- Best hubs point to best authorities.

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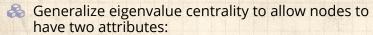
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Nutshell





- 1. Authority: how much knowledge, information, etc., held by a node on a topic.
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- Original work due to the legendary Jon Kleinberg. [2]
- Best hubs point to best authorities.
- Recursive: Hubs authoritatively link to hubs, authorities hubbishly link to other authorities.

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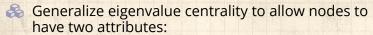
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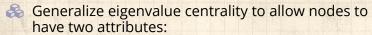
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Nutshell





- 1. Authority: how much knowledge, information, etc., held by a node on a topic.
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- Original work due to the legendary Jon Kleinberg. [2]
- Best hubs point to best authorities.
- Recursive: Hubs authoritatively link to hubs, authorities hubbishly link to other authorities.
- More: look for dense links between sets of 'good' hubs pointing to sets of 'good' authorities.
- Known as the HITS algorithm (Hyperlink-Induced Topics Search).

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Give each node two scores:

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Give each node two scores:

1. x_i = authority score for node i

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Give each node two scores:

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Nutshell





Give each node two scores:

- 1. x_i = authority score for node i
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As for eigenvector centrality, we connect the scores of neighboring nodes.

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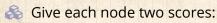
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New story I: a good authority is linked to by good hubs. The PoCSverse Measures of centrality 27 of 33

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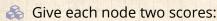
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New story I: a good authority is linked to by good hubs.

 $ext{\&}$ Means x_i should increase as $\sum_{j=1}^N a_{ji} y_j$ increases.

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- Note: indices are ji meaning j has a directed link to i.
- New story II: good hubs point to good authorities.
- Linearity assumption:

 $\vec{x} \propto A^T \vec{y}$ and $\vec{y} \propto A \vec{x}$

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So let's say we have

$$\vec{x} = c_1 A^T \vec{y}$$
 and $\vec{y} = c_2 A \vec{x}$

where c_1 and c_2 must be positive.

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So let's say we have

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Above equations combine to give

$$\vec{x} = c_1 A^T c_2 A \vec{x}$$

where
$$\lambda = c_1 c_2 > 0$$
.

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So let's say we have

$$\vec{x} = c_1 A^T \vec{y}$$
 and $\vec{y} = c_2 A \vec{x}$

where c_1 and c_2 must be positive.



Above equations combine to give

$$\vec{x} = c_1 A^T c_2 A \vec{x} = \lambda A^T A \vec{x}.$$

where $\lambda = c_1 c_2 > 0$.



It's all good: we have the heart of singular value decomposition before us ...



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 A^TA is symmetric.

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 A^TA is symmetric.



 A^TA is semi-positive definite so its eigenvalues are all ≥ 0 .

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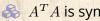
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 A^TA is symmetric.

 A^TA is semi-positive definite so its eigenvalues are all > 0.

 A^TA 's eigenvalues are the square of A's singular values.

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 A^TA is symmetric.

 A^TA is semi-positive definite so its eigenvalues are all > 0.

 A^TA 's eigenvalues are the square of A's singular values.

 A^TA' s eigenvectors form a joyful orthogonal basis.

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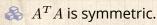
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 A^TA is semi-positive definite so its eigenvalues are all ≥ 0 .

 A^TA 's eigenvalues are the square of A's singular values.

 $\begin{cases} \&A^TA'$ s eigenvectors form a joyful orthogonal basis.

Perron-Frobenius tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries. The PoCSverse Measures of centrality 29 of 33

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Perron-Frobenius tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries.

So: linear assumption leads to a solvable system.

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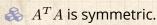
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 A^TA is semi-positive definite so its eigenvalues are all > 0.

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Perron-Frobenius tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries.

So: linear assumption leads to a solvable system.

What would be very good: find networks where we have independent measures of node 'importance' and see how importance is actually distributed.

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Measuring centrality is well motivated if hard to carry out well.

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Measuring centrality is well motivated if hard to carry out well.



We've only looked at a few major ones.

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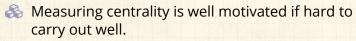
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We've only looked at a few major ones.

Methods are often taken to be more sophisticated than they really are.

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Nutshell



- Measuring centrality is well motivated if hard to carry out well.
- We've only looked at a few major ones.
- Methods are often taken to be more sophisticated than they really are.
- Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).

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Nutshell



- Measuring centrality is well motivated if hard to carry out well.
- We've only looked at a few major ones.
- Methods are often taken to be more sophisticated than they really are.
- Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).
- Focus on nodes rather than groups or modules is a homo narrativus constraint.

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Nutshell



- Measuring centrality is well motivated if hard to carry out well.
- We've only looked at a few major ones.
- Methods are often taken to be more sophisticated than they really are.
- Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).
- Focus on nodes rather than groups or modules is a homo narrativus constraint.
- Possible that better approaches will be developed.

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