## Measures of centrality

## Prof. Peter Sheridan Dodds | @peterdodds

Computational Story Lab | Vermont Complex Systems Center Vermont Advanced Computing Core | University of Vermont


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## Outline



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## How big is my node？

Basic question：how＇important＇are specific nodes and edges in a network？
\＆An important node or edge might：
1．handle a relatively large amount of the network＇s traffic（e．g．，cars，information）；
2．bridge two or more distinct groups（e．g．，liason， interpreter）；
3．be a source of important ideas，knowledge，or judgments（e．g．，supreme court decisions，an employee who＇knows where everything is＇）．
So how do we quantify such a slippery concept as importance？
8
We generate ad hoc，reasonable measures，and examine their utility ．．．

## Centrality

One possible reflection of importance is centrality. Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.
Idea of centrality comes from social networks literature ${ }^{[7]}$.
. Many flavors of centrality ...

1. Many are topological and quasi-dynamical;
2. Some are based on dynamics (e.g., traffic).

We will define and examine a few ...
8
(Later: see centrality useful in identifying communities in networks.)

## Centrality

## Degree centrality

Naively estimate importance by node degree. ${ }^{[7]}$
D Doh: assumes linearity (If node $i$ has twice as many friends as node $j$, it's twice as important.)
Doh: doesn't take in any non-local information.

## Closeness centrality

Idea: Nodes are more central if they can reach other nodes 'easily.'
8
Measure average shortest path from a node to all other nodes.
Define Closeness Centrality for node $i$ as

$$
N-1
$$

$$
\overline{\sum_{j, j \neq i}(\text { shortest distance from } i \text { to } j) .}
$$

Range is 0 (no friends) to 1 (single hub).
\& Unclear what the exact values of this measure tells us because of its ad-hocness.
General problem with simple centrality measures: what do they exactly mean?
\& Perhaps, at least, we obtain an ordering of nodes in terms of 'importance.'

## Betweenness centrality

Idea: If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion.
For each node $i$, count how many shortest paths pass through $i$.
In the case of ties, divide counts between paths.
Call frequency of shortest paths passing through node $i$ the betweenness of $i, B_{i}$.
Note: Exclude shortest paths between $i$ and other nodes.
Note: works for weighted and unweighted networks.

Consider a network with $N$ nodes and $m$ edges (possibly weighted).

- Computational goal: Find $\binom{N}{2}$ shortest paths [ between all pairs of nodes.
- Traditionally use Floyd-Warshall $\mathbb{C}$ algorithm.
- Computation time grows as $O\left(N^{3}\right)$.
- See also:

1. Dijkstra's algorithm [^ for finding shortest path between two specific nodes,
2. and Johnson's algorithm which outperforms Floyd-Warshall for sparse networks:

$$
O\left(m N+N^{2} \log N\right)
$$

Newman (2001) ${ }^{[4,5]}$ and Brandes (2001) independently derive equally fast algorithms that also compute betweenness.

- Computation times grow as:

1. $O(m N)$ for unweighted graphs;
2. and $O\left(m N+N^{2} \log N\right)$ for weighted graphs.

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## Shortest path between node $i$ and all others:

. Consider unweighted networks.
\& Use breadth-first search:

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1. Start at node $i$, giving it a distance $d=0$ from itself.
2. Create a list of all of $i$ 's neighbors and label them being at a distance $d=1$.
3. Go through list of most recently visited nodes and find all of their neighbors.
4. Exclude any nodes already assigned a distance.
5. Increment distance $d$ by 1 .
6. Label newly reached nodes as being at distance $d$.
7. Repeat steps 3 through 6 until all nodes are visited.

Record which nodes link to which nodes moving out from $i$ (former are 'predecessors' with respect to $i$ 's shortest path structure).

Runs in $O(m)$ time and gives $N-1$ shortest paths.
of Find all shortest naths in $O(m N)$ time

## Newman's Betweenness algorithm: ${ }^{[4]}$



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## Newman's Betweenness algorithm: ${ }^{[4]}$

1. Set all nodes to have a value $c_{i j}=0, j=1, \ldots$ ( $c$ for count).
2. Select one node $i$ and find shortest paths to all other $N-1$ nodes using breadth-first search.
3. Record \# equal shortest paths reaching each node.
4. Move through nodes according to their distance from $i$, starting with the furthest.

Closeness centrality
5. Travel back towards $i$ from each starting node $j$, along shortest path(s), adding 1 to every value of $c_{i \ell}$ at each node $\ell$ along the way.
6. Whenever more than one possibility exists, apportion according to total number of short paths coming through predecessors.
7. Exclude starting node $j$ and $i$ from increment.
8. Repeat steps $2-8$ for every node $i$ and obtain betweenness as $B_{j}=\sum_{i=1}^{N} c_{i j}$.

## Newman's Betweenness algorithm: ${ }^{[4]}$

. For a pure tree network, $c_{i j}$ is the number of nodes beyond $j$ from $i$ 's vantage point.

1. $j$ indexes edges,
2. and we add one to each edge as we traverse it.

For both algorithms, computation time grows as

$$
O(m N) .
$$

## Newman's Betweenness algorithm: ${ }^{[4]}$



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## Important nodes have important friends:

R Define $x_{i}$ as the 'importance' of node $i$.
Idea: $x_{i}$ depends (somehow) on $x_{j}$
if $j$ is a neighbor of $i$.
Recursive: importance is transmitted through a network.
Simplest possibility is a linear combination:

$$
x_{i} \propto \sum_{j} a_{j i} x_{j}
$$

. Assume further that constant of proportionality, $c$, is independent of $i$.
Above gives $\vec{x}=c \mathbf{A}^{\top} \vec{x}$ or $\mathbf{A}^{\top} \vec{x}=c^{-1} \vec{x}=\lambda \vec{x}$.
Eigenvalue equation based on adjacency matrix ...


8 Note: Lots of despair over size of the largest eigenvalue. ${ }^{[7]}$ Lose sight of original assumption's non-physicality.

## Important nodes have important friends:

So: solve $\mathbf{A}^{\top} \vec{x}=\lambda \vec{x}$.

We, the people, would like:

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1. $A$ has a real eigenvalue $\lambda_{1} \geq\left|\lambda_{i}\right|$ for $i=2, \ldots, N$.
2. $\lambda_{1}$ corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
3. The dominant real eigenvalue $\lambda_{1}$ is bounded by the minimum and maximum row sums of $A$ :

$$
\min _{i} \sum_{j=1}^{N} a_{i j} \leq \lambda_{1} \leq \max _{i} \sum_{j=1}^{N} a_{i j}
$$

4. All other eigenvectors have one or more negative entries.
5. The matrix $A$ can make toast.
6. Note: Proof is relatively short for symmetric matrices that are strictly positive ${ }^{[6]}$ and just non-negative ${ }^{[3]}$.

## Other Perron-Frobenius aspects:

- Assuming our network is irreducible [ $\mathbb{3}$, meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.
\& Irreducibility means largest eigenvalue's eigenvector has strictly non-negative entries.
Analogous to notion of ergodicity: every state is reachable.
(Another term: Primitive graphs and matrices.)


## Hubs and Authorities

Generalize eigenvalue centrality to allow nodes to have two attributes:

1. Authority: how much knowledge, information, etc., held by a node on a topic.
2. Hubness (or Hubosity or Hubbishness or Hubtasticness): how well a node 'knows' where to find information on a given topic.

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Best hubs point to best authorities.
8 Recursive: Hubs authoritatively link to hubs, authorities hubbishly link to other authorities.
8 More: look for dense links between sets of 'good' hubs pointing to sets of 'good' authorities.
Known as the HITS algorithm [ (Hyperlink-Induced Topics Search).

## Hubs and Authorities

- Give each node two scores:

1. $x_{i}=$ authority score for node $i$
2. $y_{i}=$ hubtasticness score for node $i$

As for eigenvector centrality, we connect the scores of neighboring nodes.
Rew story I: a good authority is linked to by good hubs.
Means $x_{i}$ should increase as $\sum_{j=1}^{N} a_{j i} y_{j}$ increases.
Note: indices are $j i$ meaning $j$ has a directed link to $i$.

8New story II: good hubs point to good authorities.
Means $y_{i}$ should increase as $\sum_{j=1}^{N} a_{i j} x_{j}$ increases.
Linearity assumption:

$$
\vec{x} \propto A^{T} \vec{y} \text { and } \vec{y} \propto A \vec{x}
$$

## Hubs and Authorities

So let's say we have

$$
\vec{x}=c_{1} A^{T} \vec{y} \text { and } \vec{y}=c_{2} A \vec{x}
$$

where $c_{1}$ and $c_{2}$ must be positive.
Above equations combine to give

$$
\vec{x}=c_{1} A^{T} c_{2} A \vec{x}=\lambda A^{T} A \vec{x}
$$

where $\lambda=c_{1} c_{2}>0$.
It's all good: we have the heart of singular value decomposition before us ...

## We can do this:

\& $A^{T} A$ is symmetric.

$A^{T} A$ is semi-positive definite so its eigenvalues are all $\geq 0$.

- $A^{T} A^{\prime}$ s eigenvalues are the square of $A^{\prime} \mathrm{s}$ singular values.
8 $A^{T} A^{\prime}$ s eigenvectors form a joyful orthogonal basis.
\& Perron-Frobenius tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries.
So: linear assumption leads to a solvable system.
. What would be very good: find networks where we have independent measures of node 'importance' and see how importance is actually distributed.


## Nutshell:

Measuring centrality is well motivated if hard to carry out well.
We've only looked at a few major ones.
Methods are often taken to be more sophisticated than they really are.
8
Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).
Focus on nodes rather than groups or modules is a homo narrativus constraint.
\& Possible that better approaches will be developed.

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