

# Measures of centrality

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Complex Networks | @networksvox  
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Background

Centrality  
measures

- Degree centrality
- Closeness centrality
- Betweenness
- Eigenvalue centrality
- Hubs and Authorities

Nutshell

References



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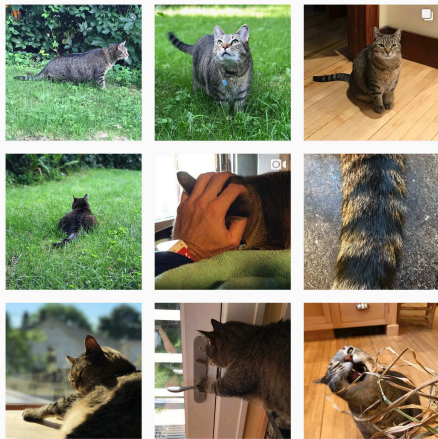


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## Special Guest Executive Producer



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# How big is my node?

 **Basic question:** how 'important' are specific nodes and edges in a network?

 An **important node** or **edge** might:

1. **handle** a relatively large amount of the network's traffic (e.g., cars, information);
2. **bridge** two or more distinct groups (e.g., liason, interpreter);
3. be a **source** of important ideas, knowledge, or judgments (e.g., supreme court decisions, an employee who 'knows where everything is').

 So how do we quantify such a slippery concept as importance?

 We generate ad hoc, reasonable measures, and examine their utility ...

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- One possible reflection of importance is **centrality**.
- Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.
- Idea of centrality comes from social networks literature<sup>[7]</sup>.
- Many flavors of centrality ...
  - Many are topological and quasi-dynamical;
  - Some are based on dynamics (e.g., traffic).
- We will define and examine a few ...
- (Later: see centrality useful in identifying communities in networks.)

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## Degree centrality


 Naively estimate importance by **node degree**. [7]


 **Doh:** assumes linearity  
(If node  $i$  has twice as many friends as node  $j$ , it's twice as important.)

 **Doh:** doesn't take in any non-local information.



# Closeness centrality


 **Idea:** Nodes are more central if they can reach other nodes 'easily.'


 Measure average shortest path from a node to all other nodes.


 Define **Closeness Centrality** for node  $i$  as

$$\frac{N - 1}{\sum_{j, j \neq i} (\text{shortest distance from } i \text{ to } j)}.$$

 Range is 0 (no friends) to 1 (single hub).








 Unclear what the exact values of this measure tells us because of its ad-hocness.

 General problem with simple centrality measures: what do they exactly mean?

 Perhaps, at least, we obtain an ordering of nodes in terms of 'importance.'



# Betweenness centrality

-  **Betweenness centrality** is based on coherence of shortest paths in a network.
-  **Idea:** If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion.
-  For each node  $i$ , count how many shortest paths pass through  $i$ .
-  In the case of ties, divide counts between paths.
-  Call frequency of shortest paths passing through node  $i$  the betweenness of  $i$ ,  $B_i$ .
-  Note: Exclude shortest paths between  $i$  and other nodes.
-  Note: works for weighted and unweighted networks.

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
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 Consider a network with  $N$  nodes and  $m$  edges (possibly weighted).


 **Computational goal:** Find  $\binom{N}{2}$  shortest paths  between all pairs of nodes.


 Traditionally use Floyd-Warshall  algorithm.

 Computation time grows as  $O(N^3)$ .

 See also:

1. Dijkstra's algorithm  for finding shortest path between two specific nodes,
2. and Johnson's algorithm  which outperforms Floyd-Warshall for sparse networks:  
 $O(mN + N^2 \log N)$ .

 Newman (2001) <sup>[4, 5]</sup> and Brandes (2001) <sup>[1]</sup> independently derive equally fast algorithms that also compute betweenness.

 Computation times grow as:

1.  $O(mN)$  for unweighted graphs;
2. and  $O(mN + N^2 \log N)$  for weighted graphs.

## Shortest path between node $i$ and all others:



Consider unweighted networks.



Use **breadth-first search**:

1. Start at node  $i$ , giving it a distance  $d = 0$  from itself.
2. Create a list of all of  $i$ 's neighbors and label them being at a distance  $d = 1$ .
3. Go through list of most recently visited nodes and find all of their neighbors.
4. Exclude any nodes already assigned a distance.
5. Increment distance  $d$  by 1.
6. Label newly reached nodes as being at distance  $d$ .
7. Repeat steps 3 through 6 until all nodes are visited.



Record which nodes link to which nodes moving out from  $i$  (former are 'predecessors' with respect to  $i$ 's shortest path structure).



Runs in  $O(m)$  time and gives  $N - 1$  shortest paths.



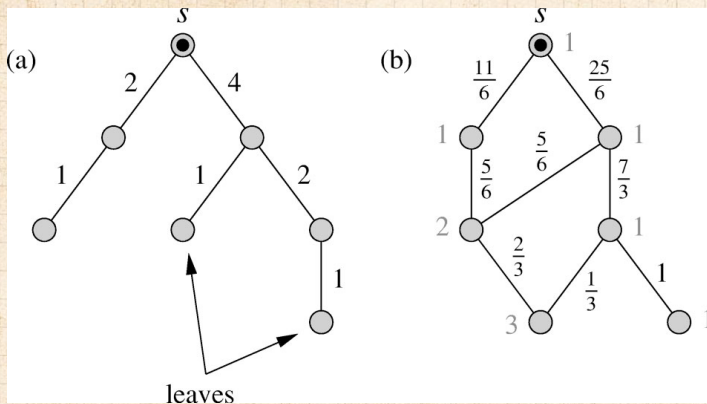
Find all shortest paths in  $O(mN)$  time



# Newman's Betweenness algorithm: [4]

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## Newman's Betweenness algorithm: [4]

1. Set all nodes to have a value  $c_{ij} = 0, j = 1, \dots$  ( $c$  for count).
2. Select one node  $i$  and find **shortest paths** to all other  $N - 1$  nodes using breadth-first search.
3. Record # equal shortest paths reaching each node.
4. Move through nodes according to their distance from  $i$ , starting with the furthest.
5. Travel **back towards  $i$  from each starting node  $j$** , along shortest path(s), adding 1 to every value of  $c_{i\ell}$  at each node  $\ell$  along the way.
6. Whenever more than one possibility exists, apportion **according to total number of short paths** coming through predecessors.
7. Exclude starting node  $j$  and  $i$  from increment.
8. Repeat steps 2–8 for every node  $i$  and obtain **betweenness** as  $B_j = \sum_{i=1}^N c_{ij}$ .



# Newman's Betweenness algorithm: [4]

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- For a **pure tree network**,  $c_{ij}$  is the number of nodes beyond  $j$  from  $i$ 's vantage point.
- Same algorithm for computing drainage area in river networks (with 1 added across the board).
- For **edge betweenness**, use exact same algorithm but now
  - $j$  indexes edges,
  - and we add one to each edge as we traverse it.
- For both algorithms, computation time grows as

$$O(mN).$$

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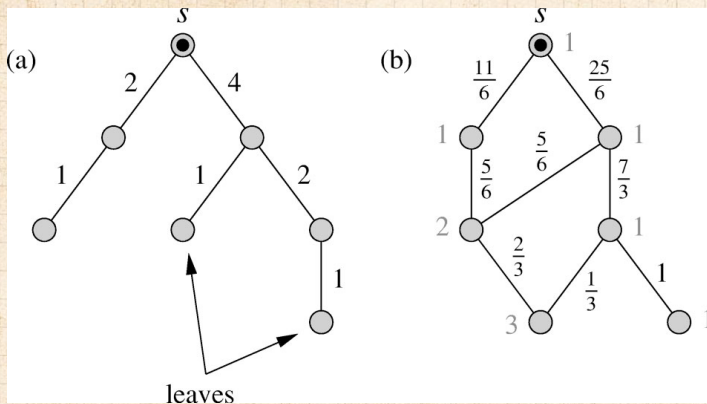
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# Newman's Betweenness algorithm: [4]



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# Important nodes have important friends:

- Define  $x_i$  as the 'importance' of node  $i$ .
- Idea:  $x_i$  depends (somehow) on  $x_j$  if  $j$  is a neighbor of  $i$ .
- Recursive:** importance is transmitted through a network.
- Simplest possibility is a linear combination:

$$x_i \propto \sum_j a_{ji} x_j$$

- Assume further that constant of proportionality,  $c$ , is independent of  $i$ .
- Above gives  $\vec{x} = c\mathbf{A}^T\vec{x}$  or  $\mathbf{A}^T\vec{x} = c^{-1}\vec{x} = \lambda\vec{x}$ .
- Eigenvalue equation based on adjacency matrix ...
- Note: Lots of despair over size of the largest eigenvalue. <sup>[7]</sup> Lose sight of original assumption's non-physicality.



# Important nodes have important friends:

- So: solve  $\mathbf{A}^T \vec{x} = \lambda \vec{x}$ .
- But which eigenvalue and eigenvector?
- We, the people, would like:
  1. A unique solution. ✓
  2.  $\lambda$  to be real. ✓
  3. Entries of  $\vec{x}$  to be real. ✓
  4. Entries of  $\vec{x}$  to be non-negative. ✓
  5.  $\lambda$  to actually mean something ... (maybe too much)
  6. Values of  $x_i$  to mean something  
(what does an observation that  $x_3 = 5x_7$  mean?)  
(maybe only ordering is informative ...)  
(maybe too much)
  7.  $\lambda$  to equal 1 would be nice ... (maybe too much)
  8. Ordering of  $\vec{x}$  entries to be robust to reasonable modifications of linear assumption (maybe too much)
- We rummage around in bag of tricks and pull out the Perron-Frobenius theorem ...

## Perron-Frobenius theorem: If an $N \times N$ matrix $A$ has non-negative entries then:

1.  $A$  has a real eigenvalue  $\lambda_1 \geq |\lambda_i|$  for  $i = 2, \dots, N$ .
2.  $\lambda_1$  corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
3. The dominant real eigenvalue  $\lambda_1$  is bounded by the minimum and maximum row sums of  $A$ :

$$\min_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max_i \sum_{j=1}^N a_{ij}$$

4. All other eigenvectors have one or more negative entries.
5. The matrix  $A$  can make toast.
6. Note: Proof is relatively short for symmetric matrices that are strictly positive <sup>[6]</sup> and just non-negative <sup>[3]</sup>.



# Other Perron-Frobenius aspects:

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 Assuming our network is irreducible , meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.

 Irreducibility means largest eigenvalue's eigenvector has strictly non-negative entries.


 Analogous to notion of ergodicity: every state is reachable.

 (Another term: **Primitive** graphs and matrices.)








# Hubs and Authorities


 Generalize eigenvalue centrality to allow nodes to have two attributes:

1. **Authority**: how much knowledge, information, etc., held by a node on a topic.
2. **Hubness (or Hubosity or Hubbishness or Hubtasticness)**: how well a node 'knows' where to find information on a given topic.

 Original work due to the legendary Jon Kleinberg. <sup>[2]</sup>

 Best hubs point to best authorities.

 **Recursive**: Hubs authoritatively link to hubs, authorities hubbishly link to other authorities.

 **More**: look for dense links between sets of 'good' hubs pointing to sets of 'good' authorities.

 Known as the HITS algorithm   
(Hyperlink-Induced Topics Search).





# Hubs and Authorities



Give each node two scores:

1.  $x_i$  = **authority score** for node  $i$
2.  $y_i$  = **hubtasticness score** for node  $i$



As for eigenvector centrality, we connect the scores of neighboring nodes.



New story I: a good authority is linked to by good hubs.



Means  $x_i$  should **increase** as  $\sum_{j=1}^N a_{ji} y_j$  **increases**.



**Note:** indices are  $ji$  meaning  $j$  has a directed link to  $i$ .



New story II: good hubs point to good authorities.




Means  $y_i$  should **increase** as  $\sum_{j=1}^N a_{ij} x_j$  **increases**.



Linearity assumption:


$$\vec{x} \propto A^T \vec{y} \text{ and } \vec{y} \propto A \vec{x}$$



 So let's say we have


$$\vec{x} = c_1 A^T \vec{y} \text{ and } \vec{y} = c_2 A \vec{x}$$

where  $c_1$  and  $c_2$  must be positive.

 Above equations combine to give

$$\vec{x} = c_1 A^T c_2 A \vec{x} = \lambda A^T A \vec{x}.$$

where  $\lambda = c_1 c_2 > 0$ .

 **It's all good:** we have the heart of singular value decomposition before us ...

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# We can do this:

-   $A^T A$  is symmetric.
-   $A^T A$  is semi-positive definite so its eigenvalues are all  $\geq 0$ .
-   $A^T A$ 's eigenvalues are the square of  $A$ 's singular values.
-   $A^T A$ 's eigenvectors form a joyful orthogonal basis.
-  Perron-Frobenius tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries.
-  So: linear assumption leads to a solvable system.
-  What would be very good: find networks where we have independent measures of node 'importance' and see how importance is actually distributed.

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## Nutshell:

- Measuring centrality is well motivated if hard to carry out well.
- We've only looked at a few major ones.
- Methods are often taken to be more sophisticated than they really are.
- Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).
- Focus on nodes rather than groups or modules is a homo narrativus constraint.
- Possible that better approaches will be developed.

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