Measures of centrality

Last updated: 2018/03/23, 12:08:15

Complex Networks | @networksvox CSYS/MATH 303, Spring, 2018

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Centrality

Degree centrality

Eigenvalue centrality Hubs and Authorities





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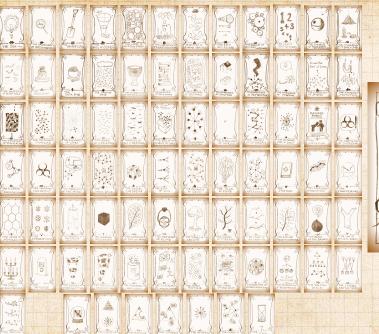
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Basic question: how 'important' are specific nodes and edges in a network?



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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

1. handle a relatively large amount of the network's traffic (e.g., cars, information);

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

- 1. handle a relatively large amount of the network's traffic (e.g., cars, information);
- bridge two or more distinct groups (e.g., liason, interpreter);

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

- 1. handle a relatively large amount of the network's traffic (e.g., cars, information);
- bridge two or more distinct groups (e.g., liason, interpreter);
- 3. be a source of important ideas, knowledge, or judgments (e.g., supreme court decisions, an employee who 'knows where everything is').

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Basic question: how 'important' are specific nodes and edges in a network?



An important node or edge might:

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So how do we quantify such a slippery concept as importance?



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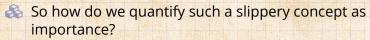


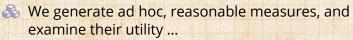
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One possible reflection of importance is centrality.

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One possible reflection of importance is centrality.



Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.

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- - One possible reflection of importance is centrality.
- Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.
- Idea of centrality comes from social networks literature [7].

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- One possible reflection of importance is centrality.
- Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.
- ldea of centrality comes from social networks literature [7].
- Many flavors of centrality ...
 - 1. Many are topological and quasi-dynamical;
 - 2. Some are based on dynamics (e.g., traffic).

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 - 1. Many are topological and quasi-dynamical;
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- We will define and examine a few ...



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- Many flavors of centrality ...
 - 1. Many are topological and quasi-dynamical;
 - 2. Some are based on dynamics (e.g., traffic).
- We will define and examine a few ...
- (Later: see centrality useful in identifying communities in networks.)

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Degree centrality



A Naively estimate importance by node degree. [7]

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Degree centrality



Naively estimate importance by node degree. [7]



Doh: assumes linearity (If node i has twice as many friends as node j, it's twice as important.)

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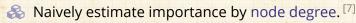
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Degree centrality



Doh: assumes linearity (If node i has twice as many friends as node j, it's twice as important.)

Doh: doesn't take in any non-local information.

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🚵 Idea: Nodes are more central if they can reach other nodes 'easily.'

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Idea: Nodes are more central if they can reach other nodes 'easily.'

Measure average shortest path from a node to all other nodes.

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- ldea: Nodes are more central if they can reach other nodes 'easily.'
- Measure average shortest path from a node to all other nodes.
- Define Closeness Centrality for node i as

 $\frac{N-1}{\sum_{i,j\neq i} (\text{shortest distance from } i \text{ to } j)}.$

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Range is 0 (no friends) to 1 (single hub).

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- Range is 0 (no friends) to 1 (single hub).
- Unclear what the exact values of this measure tells us because of its ad-hocness.

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- General problem with simple centrality measures: what do they exactly mean?

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- Range is 0 (no friends) to 1 (single hub).
- Unclear what the exact values of this measure tells us because of its ad-hocness.
- General problem with simple centrality measures: what do they exactly mean?
- Perhaps, at least, we obtain an ordering of nodes in terms of 'importance.'

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Betweenness centrality



Betweenness centrality is based on coherence of shortest paths in a network.

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Betweenness centrality is based on coherence of shortest paths in a network.

Idea: If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion.

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Betweenness centrality is based on coherence of shortest paths in a network.

ldea: If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion.

For each node *i*, count how many shortest paths pass through *i*.

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- Note: Exclude shortest paths between *i* and other nodes.
- Note: works for weighted and unweighted networks.

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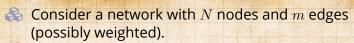
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Computational goal: Find $\binom{N}{2}$ shortest paths between all pairs of nodes.

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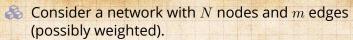
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Computational goal: Find $\binom{N}{2}$ shortest paths between all pairs of nodes.

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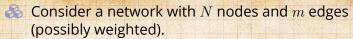
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Computational goal: Find $\binom{N}{2}$ shortest paths between all pairs of nodes.

& Computation time grows as $O(N^3)$.

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- Solution Consider a network with N nodes and m edges (possibly weighted).
- Computational goal: Find $\binom{N}{2}$ shortest paths between all pairs of nodes.
- Traditionally use Floyd-Warshall
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- & Computation time grows as $O(N^3)$.
- 🙈 See also:
 - 1. Dijkstra's algorithm of for finding shortest path between two specific nodes,

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- Solution Consider a network with N nodes and m edges (possibly weighted).
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- & Computation time grows as $O(N^3)$.
- See also:
 - Dijkstra's algorithm of for finding shortest path between two specific nodes,
 - 2. and Johnson's algorithm \square which outperforms Floyd-Warshall for sparse networks: $O(mN + N^2 \log N)$.

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Computational goal: Find $\binom{N}{2}$ shortest paths between all pairs of nodes.

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🚳 See also:

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Newman (2001) [4,5] and Brandes (2001) [1] independently derive equally fast algorithms that also compute betweenness.

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Computation times grow as:

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Computation times grow as:

1. O(mN) for unweighted graphs;

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Computation times grow as:

1. O(mN) for unweighted graphs;

2. and $O(mN + N^2 \log N)$ for weighted graphs.

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Consider unweighted networks.

Use breadth-first search:

Record which nodes link to which nodes moving out from *i* (former are 'predecessors' with respect to *i*'s shortest path structure)

Runs in O(m) time and gives N=1 shortest paths.

Find all shortest naths in O m V time

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Consider unweighted networks.



Use breadth-first search:

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d=1.

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Consider unweighted networks.



Use breadth-first search:

- 1. Start at node i, giving it a distance d = 0 from itself.
- 2. Create a list of all of i's neighbors and label them being at a distance d=1.
- 3. Go through list of most recently visited nodes and find all of their neighbors.

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- 4. Exclude any nodes already assigned a distance.

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- 4. Exclude any nodes already assigned a distance.
- 5. Increment distance d by 1.

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- 6. Label newly reached nodes as being at distance d.

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- 6. Label newly reached nodes as being at distance d.
- Repeat steps 3 through 6 until all nodes are visited.

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Record which nodes link to which nodes moving out from i (former are 'predecessors' with respect to i's shortest path structure).



Runs in O(m) time and gives N-1 shortest paths.

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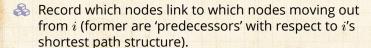


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Runs in O(m) time and gives N-1 shortest paths.

Find all shortest paths in O(mN) time

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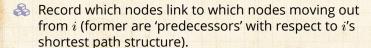


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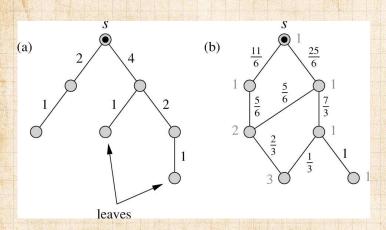
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Newman's Betweenness algorithm: [4]



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2. Select one node i and find shortest paths to all other N-1 nodes using breadth-first search.

- 3. Record #equal shortest paths reaching each node.
- 4. Move through nodes according to their distance from *i*, starting with the furthest.
- 5. Travel-back towards ϵ from each starting node j, along shortest path(s), adding 1 to every value of $c_{i\ell}$ at each node ℓ along the way.
- 6. Whenever more than one possibility exists, apportion according to total number of short paths coming through predecessors.
- 7. Exclude starting node j and i from increment.
- 8. Repeat steps 2+8 for every node 7 and obtain

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2. Select one node i and find shortest paths to all other N-1 nodes using breadth-first search.

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- 6. Whenever more than one possibility exists, apportion according to total number of short paths coming through predecessors.
- 7. Exclude starting node *j* and *i* from increment.
- 8. Repeat steps 2–8 for every node i and obtain betweenness as $B_j = \sum_{i=1}^{N} c_{ij}$.

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Newman's Betweenness algorithm: [4]

 $\red {\Bbb S}$ For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.

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Newman's Betweenness algorithm: [4]

For a pure tree network, c_{ij} is the number of nodes beyond j from i's vantage point.

Same algorithm for computing drainage area in river networks (with 1 added across the board).

use exact same algorithm

and we add one to each edge as we traverse it

For but algorithms computation time grows as

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Newman's Betweenness algorithm: [4]

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O(mN).

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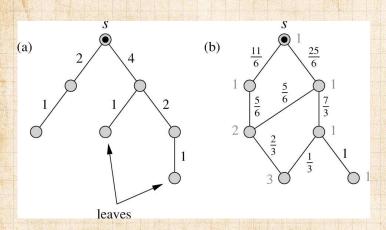
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Newman's Betweenness algorithm: [4]



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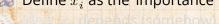
Nutshell







Define x_i as the 'importance' of node i.



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 \triangle Define x_i as the 'importance' of node i.



 \mathbb{R} Idea: x_i depends (somehow) on x_i if j is a neighbor of i.



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Assume further that constant of proportionality, c, is independent of i.

Above gives $r = d\mathbf{A}^{T} = \mathbf{or} = \mathbf{A}^{T} = r = r = \lambda T$

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Lose sight of original assumption's non-physicality.

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



But which eigenvalue and eigenvector?



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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

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& We, the people, would like:

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.

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& We, the people, would like:

1. A unique solution.

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- So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.
- - But which eigenvalue and eigenvector?
- & We, the people, would like:
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 - 2. λ to be real.

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So: solve $\mathbf{A}^{\mathsf{T}}\vec{x} = \lambda \vec{x}$.



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- 4. Entries of \vec{x} to be non-negative.

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- 5. λ to actually mean something ...

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- 8. Ordering of \vec{x} entries to be robust to reasonable modifications of linear assumption

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We rummage around in bag of tricks and pull out the Perron-Frobenius theorem ...













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We rummage around in bag of tricks and pull out the Perron-Frobenius theorem ...



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- A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for i = 2, ..., N.
- λ₁ corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
- 3. The dominant real eigenvalue λ_1 is bounded by the minimum and maximum row sums of A:

$$\min_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max_i \sum_{j=1}^N a_i$$

4. All other eigenvectors have one or more negative entries.

6. Note: Proof is relatively short for symmetric matrices that are strictly positive and just non-negative.

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Perron-Frobenius theorem: \square If an $N \times N$ matrix A has non-negative entries then:

- 1. A has a real eigenvalue $\lambda_1 \geq |\lambda_i|$ for $i=2,\ldots,N$.
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$$\min\nolimits_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max\nolimits_i \sum_{j=1}^N a_{ij}$$

- 4. All other eigenvectors have one or more negative entries.
- 5. The matrix *A* can make toast.
- 6. Note: Proof is relatively short for symmetric matrices that are strictly positive [6] and just non-negative [3].

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Other Perron-Frobenius aspects:



Assuming our network is irreducible , meaning there is only one component, is reasonable: just

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Other Perron-Frobenius aspects:

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Other Perron-Frobenius aspects:

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Generalize eigenvalue centrality to allow nodes to have two attributes:

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- 8
 - Generalize eigenvalue centrality to allow nodes to have two attributes:
 - 1. Authority: how much knowledge, information, etc., held by a node on a topic.

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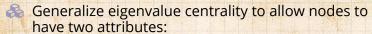
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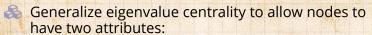
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- Known as the HITS algorithm (Hyperlink-Induced Topics Search).

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Give each node two scores:

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Give each node two scores:

1. x_i = authority score for node i

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- \iff Means y_i should increase as $\sum_{j=1}^N a_{ij} x_j$ increases.
- Linearity assumption:

 $\vec{x} \propto A^T \vec{y}$ and $\vec{y} \propto A \vec{x}$



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So let's say we have

$$\vec{x} = c_1 A^T \vec{y}$$
 and $\vec{y} = c_2 A \vec{x}$

where c_1 and c_2 must be positive.

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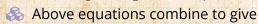


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where $\lambda = c_1 c_2 > 0$.

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So let's say we have

$$\vec{x} = c_1 A^T \vec{y}$$
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Above equations combine to give

$$\vec{x} = c_1 A^T c_2 A \vec{x} = \lambda A^T A \vec{x}.$$

where $\lambda = c_1 c_2 > 0$.



It's all good: we have the heart of singular value decomposition before us ...

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 A^TA is symmetric.

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 A^TA is symmetric.

 A^TA is semi-positive definite so its eigenvalues are all > 0.

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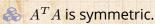
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 A^TA is semi-positive definite so its eigenvalues are all > 0.

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 $A^T A$'s eigenvectors form a joyful orthogonal basis.

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- 🗞 So: linear assumption leads to a solvable system.
- What would be very good: find networks where we have independent measures of node 'importance' and see how importance is actually distributed.

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Measuring centrality is well motivated if hard to carry out well.

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Measuring centrality is well motivated if hard to carry out well.



We've only looked at a few major ones.

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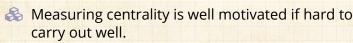
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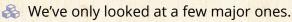
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Methods are often taken to be more sophisticated than they really are.

Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).

Focus on nodes rather than groups or modules is a homo narrativus constraint.

Possible that better approaches will be developed

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