Contagion

Complex Networks | @networksvox CSYS/MATH 303, Spring, 2016

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Basic Contagion Models

Global spreading condition

Social Contagion Models

> letwork version ll-to-all networks

Theory

Spreading possibility Spreading probability Physical explanation







These slides are brought to you by:



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Global spreading

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Outline

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Social Contagion Models Network version All-to-all networks

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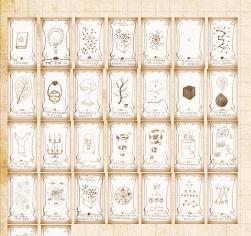
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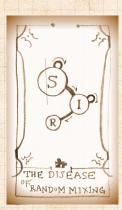
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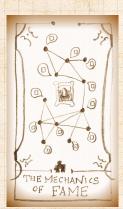
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Some large questions concerning network contagion:

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- 1. For a given spreading mechanism on a given network, what's the probability that there will be global spreading?

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- 2. If spreading does take off, how far will it go?

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Some large questions concerning network contagion:

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- 5. What if the seed is one or many nodes?

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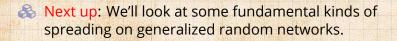






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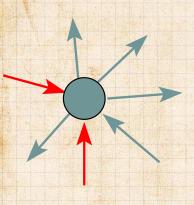
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uninfected infected



General spreading mechanism:

State of node i depends on history of i and i's neighbors' states.

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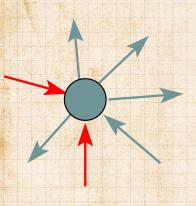
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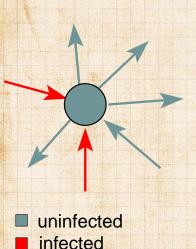
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General spreading mechanism:

State of node i depends on history of i and i's neighbors' states.



Doses of entity may be stochastic and history-dependent.



May have multiple, interacting entities spreading at once.

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For random networks, we know local structure is pure branching.

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For random networks, we know local structure is pure branching.

Successful spreading is a contingent on single edges infecting nodes.

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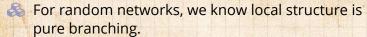
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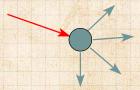


Successful spreading is : contingent on single edges infecting nodes.

Success



Failure:



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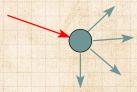
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Success







Focus on binary case with edges and nodes either infected or not.

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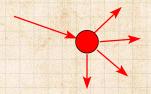


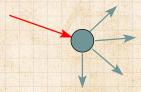
For random networks, we know local structure is pure branching.

Successful spreading is a contingent on single edges infecting nodes.

Success







Focus on binary case with edges and nodes either infected or not.

First big question: for a given network and contagion process, can global spreading from a single seed occur?

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We need to find: [5]

R = the average # of infected edges that one random infected edge brings about.

Call R the gain ratio.

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Define B_{k_1} as the probability that a node of degree k is infected by a single infected edge.



$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{\frac{kP_k}{\langle k \rangle}}{\text{prob. of }}$$
prob. of connecting to a degree k node

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$$B_{k1}$$
Prob. of infection

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$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{kP_k}{\underbrace{\langle k \rangle}}$$
 prob. of connecting to a degree k node

outgoing infected edges

Prob. of infection

$$+\sum_{k=0}^{\infty}\frac{\widehat{kP_k}}{\langle k\rangle}$$

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$$\underbrace{(k-1)}_{\text{\# outgoing infected edges}}$$

$$\frac{D_{k1}}{\text{Prob. of infection}}$$

$$+\sum_{k=0}^{\infty} \frac{\widehat{kP_k}}{\langle k \rangle} \bullet \underbrace{0}_{\mbox{infected edges}}$$

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infected

edges



$$\mathbf{R} = \sum_{k=0}^{\infty} \underbrace{\frac{kP_k}{\langle k \rangle}}_{\text{prob. of connecting to a degree k node}}$$

$$\underbrace{(k-1)}_{\text{\# outgoing infected edges}}$$

Prob. of

infection

$$\underbrace{0}_{\text{\# outgoing infected} \atop \text{edges}} \bullet \underbrace{\left(1-B_{k1}\right)}_{\text{Prob. of no infection} }$$

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Our global spreading condition is then:

$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} > 1.$$

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Our global spreading condition is then:

$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} > 1.$$



$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) = \frac{\langle k(k-1) \rangle}{\langle k \rangle} > 1.$$

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Our global spreading condition is then:

$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} > 1.$$

& Case 1: If $B_{k1} = 1$ then

$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) = \frac{\langle k(k-1) \rangle}{\langle k \rangle} > 1.$$

Good: This is just our giant component condition again.

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Case 2:



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Solution Case 2: If $B_{k_1} = \beta < 1$

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& Case 2: If $B_{k1} = \beta < 1$ then

$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet \beta > 1.$$



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$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet \beta > 1.$$



 \triangle A fraction (1- β) of edges do not transmit infection.

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$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet \beta > 1.$$



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Analogous phase transition to giant component case but critical value of $\langle k \rangle$ is increased.



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Aka bond percolation .

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- \triangle A fraction (1- β) of edges do not transmit infection.
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- Aka bond percolation .
- & Resulting degree distribution \tilde{P}_k :

$$\tilde{P}_k = \beta^k \sum_{i=k}^{\infty} {i \choose k} (1-\beta)^{i-k} P_i.$$

Insert question from assignment 9 1

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Insert question from assignment 9 2



 \Longrightarrow We can show $F_{\tilde{D}}(x) = F_{P}(\beta x + 1 - \beta)$.

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Cases 3, 4, 5, ...: White allow B. Holdepend on

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 \mathbb{R} Cases 3, 4, 5, ...: Now allow B_{k1} to depend on k

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Asymmetry: Transmission along an edge depends on node's degree at other end.

Possibility, Ba increases with a.

Possibilità la la fot monotoria

But it is plausified epresentation of their

kind of scicial comparion.

More well connected people are harder to

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 \clubsuit Cases 3, 4, 5, ...: Now allow B_{k1} to depend on k

Asymmetry: Transmission along an edge depends on node's degree at other end.

 \mathfrak{S} Possibility: B_{k1} increases with k... unlikely.

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3 Cases 3, 4, 5, ...: Now allow B_{k1} to depend on k

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 \S Possibility: B_{k1} is not monotonic in k...

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 $\red {\Bbb S}$ Cases 3, 4, 5, ...: Now allow B_{k1} to depend on k

Asymmetry: Transmission along an edge depends on node's degree at other end.

 $\red {\Bbb S}$ Possibility: B_{k1} increases with k... unlikely.

 $\red {\Bbb R}$ Possibility: B_{k1} is not monotonic in k... unlikely.

diffuence:

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 $B_{k_1} \setminus S$ is a plausible representation of a simple kind of social contagion.

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- \mathbb{R} Cases 3, 4, 5, ...: Now allow B_{k1} to depend on k
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- The story:

More well connected people are harder to influence.

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 \clubsuit Example: $B_{k1} = 1/k$.

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$$\mathbf{R} = \sum_{k=1}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1}$$

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 \clubsuit Example: $B_{k1} = 1/k$.



$$\mathbf{R} = \sum_{k=1}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} = \sum_{k=1}^{\infty} (k-1) \bullet \frac{k P_k}{\langle k \rangle} \bullet \frac{1}{k}$$

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 \clubsuit Example: $B_{k,1} = 1/k$.



$$\begin{split} \mathbf{R} &= \sum_{k=1}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} = \sum_{k=1}^{\infty} (k-1) \bullet \frac{k P_k}{\langle k \rangle} \bullet \frac{1}{k} \\ &= \sum_{k=1}^{\infty} \frac{P_k}{\langle k \rangle} \bullet (k-1) \end{split}$$

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 \mathbb{R} Since R is always less than 1, no spreading can occur for this mechanism.



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 \clubsuit Example: $B_{k,1} = 1/k$.



$$\begin{split} \mathbf{R} &= \sum_{k=1}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} = \sum_{k=1}^{\infty} (k-1) \bullet \frac{k P_k}{\langle k \rangle} \bullet \frac{1}{k} \\ &= \sum_{k=1}^{\infty} \frac{P_k}{\langle k \rangle} \bullet (k-1) = 1 - \frac{1 - P_0}{\langle k \rangle} \end{split}$$

- \mathbb{R} Since R is always less than 1, no spreading can occur for this mechanism.
- \bigotimes Decay of B_{k1} is too fast.

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- \mathbb{R} Since R is always less than 1, no spreading can occur for this mechanism.
- \bigotimes Decay of B_{k1} is too fast.
- Result is independent of degree distribution.

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- Example: $B_{k1} = H(\frac{1}{k} \phi)$ where $0 < \phi \le 1$ is a threshold and H is the Heaviside function 2.

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- **Example:** $B_{k1} = H(\frac{1}{h} \phi)$ where $0 < \phi \le 1$ is a threshold and H is the Heaviside function .
- Infection only occurs for nodes with low degree.

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Example: $B_{k,1} = H(\frac{1}{k} - \phi)$ where $0 < \phi \le 1$ is a threshold and H is the Heaviside function .

Infection only occurs for nodes with low degree.

Call these nodes vulnerables: they flip when only one of their friends flips. COCONUTS

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Example: $B_{k1} = H(\frac{1}{k} - \phi)$ where $0 < \phi \le 1$ is a threshold and H is the Heaviside function \square .

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$$\mathbf{R} = \sum_{k=1}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1}$$

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Example: $B_{k1} = H(\frac{1}{k} - \phi)$ where $0 < \phi \le 1$ is a threshold and H is the Heaviside function \mathcal{C} .

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$$=\sum_{k=1}^{\lfloor\frac{1}{\phi}\rfloor}(k-1)\bullet\frac{kP_k}{\langle k\rangle}\quad\text{where }\lfloor\cdot\rfloor\text{ means floor.}$$



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The uniform threshold model global spreading condition:

$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{\phi} \rfloor} (k-1) \bullet \frac{kP_k}{\langle k \rangle} > 1.$$

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The uniform threshold model global spreading condition:

$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{\phi} \rfloor} (k-1) \bullet \frac{k P_k}{\langle k \rangle} > 1.$$

 \Leftrightarrow As $\phi \to 1$, all nodes become resilient and $r \to 0$.

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 $As \phi \rightarrow 1$, all nodes become resilient and $r \rightarrow 0$.

As $\phi \rightarrow 0$, all nodes become vulnerable and the contagion condition matches up with the giant component condition.

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- & Key: If we fix ϕ and then vary $\langle k \rangle$, we may see two phase transitions.

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- As $\phi \rightarrow 0$, all nodes become vulnerable and the contagion condition matches up with the giant component condition.
- & Key: If we fix ϕ and then vary $\langle k \rangle$, we may see two phase transitions.
- Added to our standard giant component transition, we will see a cut off in spreading as nodes become more connected.

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Virtual contagion: Corrupted Blood ☑, a 2005 virtual plague in World of Warcraft:



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Some important models (recap from CSYS 300)



Tipping models—Schelling (1971) [11, 12, 13]

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Some important models (recap from CSYS 300)



Tipping models—Schelling (1971) [11, 12, 13]

Simulation on checker boards.

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- Threshold models—Granovetter (1978) [8]

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Some important models (recap from CSYS 300)

- Tipping models—Schelling (1971) [11, 12, 13]
 - Simulation on checker boards.
 - Idea of thresholds.
- Threshold models—Granovetter (1978) [8]
- A Herding models—Bikhchandani et al. (1992) [1, 2]

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Some important models (recap from CSYS 300)

- Tipping models—Schelling (1971) [11, 12, 13]
 - Simulation on checker boards.
 - Idea of thresholds.
- Threshold models—Granovetter (1978) [8]
- A Herding models—Bikhchandani et al. (1992) [1, 2]
 - Social learning theory, Informational cascades,...

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Original work:



"A simple model of global cascades on random networks"

Duncan J. Watts, Proc. Natl. Acad. Sci., 99, 5766-5771, 2002. [15]

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Mean field Granovetter model → network model

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Mean field Granovetter model → network model Individuals now have a limited view of the world

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Interactions between individuals now represented by a network

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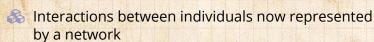
Theory

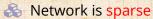
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Interactions between individuals now represented by a network

Network is sparse

 \mathbb{A} Individual i has k_i contacts

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- Interactions between individuals now represented by a network
- Network is sparse
- Individual i has k_i contacts
- Influence on each link is reciprocal and of unit weight

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Interactions between individuals now represented by a network

Network is sparse

Individual i has k_i contacts

Influence on each link is reciprocal and of unit weight

 \Leftrightarrow Each individual i has a fixed threshold ϕ_i

Synchronerus, discrete time updating
Individual becomes active when submitted discrete bontaces active and active bontaces active active bontaces active

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Interactions between individuals now represented by a network

Network is sparse

Individual i has k_i contacts

Influence on each link is reciprocal and of unit weight

Each individual i has a fixed threshold ϕ_i

Individuals repeatedly poll contacts on network

Synchronous, discrete time updating

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- Network is sparse
- Individual i has k_i contacts
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- Synchronous, discrete time updating
- A Individual i becomes active when number of active contacts $a_i \geq \phi_i k_i$

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- Interactions between individuals now represented by a network
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- A lndividual i becomes active when number of active contacts $a_i \ge \phi_i k_i$
- Activation is permanent (SI)

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All nodes have threshold $\phi = 0.2$.

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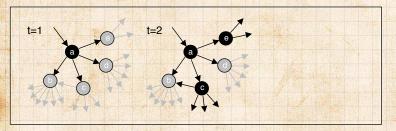
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All nodes have threshold $\phi = 0.2$.

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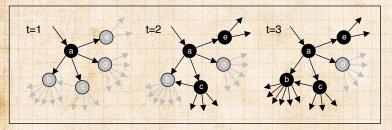
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All nodes have threshold $\phi = 0.2$.

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$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{\phi} \rfloor} \frac{k P_k}{\langle k \rangle} \bullet (k-1) > 1$$

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Recall definition: individuals who can be activated by just one contact being active are vulnerables.

$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{\phi} \rfloor} \frac{k P_k}{\langle k \rangle} \bullet (k-1) > 1.$$

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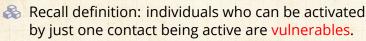
Theory

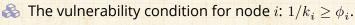
Spreading possibility Spreading probability Physical explanation











$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{p} \rfloor} \frac{k P_k}{\langle k \rangle} \bullet (k-1) > 1.$$

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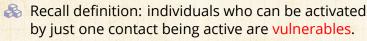
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 \clubsuit The vulnerability condition for node $i: 1/k_i \geq \phi_i$.

& Means # contacts $k_i \leq |1/\phi_i|$.

$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{p} \rfloor} \frac{k P_k}{\langle k \rangle} \bullet (k-1) > 1.$$

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- Key: For global spreading events (cascades) on random networks, must have a global component of vulnerables [15]



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The most gullible

Vulnerables:

- Recall definition: individuals who can be activated by just one contact being active are vulnerables.
- \clubsuit The vulnerability condition for node i: $1/k_i \geq \phi_i$.
- Means # contacts $k_i \leq |1/\phi_i|$.
- Key: For global spreading events (cascades) on random networks, must have a global component of vulnerables [15]
- \clubsuit For a uniform threshold ϕ , our global spreading condition tells us when such a component exists:

$$\mathbf{R} = \sum_{k=1}^{\lfloor \frac{1}{\phi} \rfloor} \frac{k P_k}{\langle k \rangle} \bullet (k-1) > 1.$$

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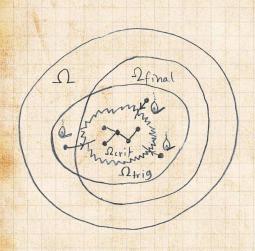
Spreading possibility Spreading probability Physical explanation







Example random network structure:



Ω_{crit} = critical mass = global vulnerable component

Ω_{trig} =
 triggering
 component

Ω_{final} = potential extent of spread

 Ω = entire network

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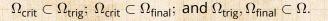
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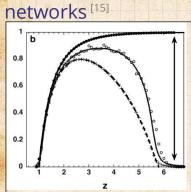
Spreading possibility Spreading probability Physical explanation Final size







Global spreading events on random



 $z = \langle k \rangle$

Top curve: final fraction infected if successful.

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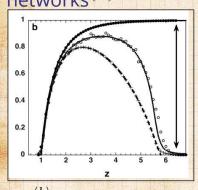
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Global spreading events on random networks [15]



$$z=\langle k
angle$$

Top curve: final fraction infected if successful.







Bottom curve: fractional size of vulnerable subcomponent. [15]

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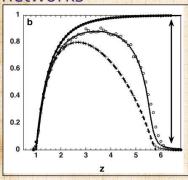
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$$z = \langle k \rangle$$



Top curve: final fraction infected if successful.



Middle curve: chance of starting a global spreading event (cascade).



Bottom curve: fractional size of vulnerable subcomponent. [15]

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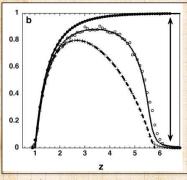
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Top curve: final fraction infected if successful.

Middle curve: chance of starting a global spreading event (cascade).

Bottom curve: fractional size of vulnerable subcomponent. [15]

 $z = \langle k \rangle$

Global spreading events occur only if size of vulnerable subcomponent > 0.

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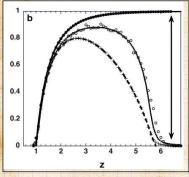
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- Top curve: final fraction infected if successful.
- Middle curve: chance of starting a global spreading event (cascade).
 - Bottom curve: fractional size of vulnerable subcomponent. [15]

 $z = \langle k \rangle$

- Global spreading events occur only if size of vulnerable subcomponent > 0.
- System is robust-yet-fragile just below upper boundary [3, 4, 14]

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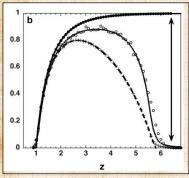
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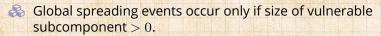






- Top curve: final fraction infected if successful.
- Middle curve: chance of starting a global spreading event (cascade).
 - Bottom curve: fractional size of vulnerable subcomponent. [15]

 $z = \langle k \rangle$



System is robust-yet-fragile just below upper boundary [3, 4, 14]

"Ignorance" facilitates spreading.

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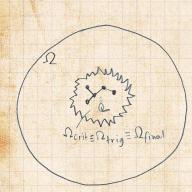
Theory



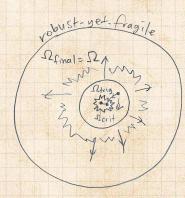




Cascades on random networks



Above lower phase transition



Just below upper phase transition

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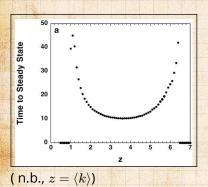
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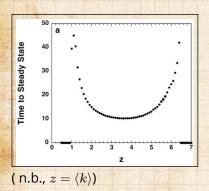
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Two phase transitions.

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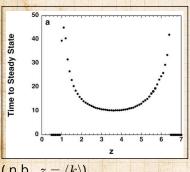
Spreading possibility Spreading probability Physical explanation













Two phase transitions.

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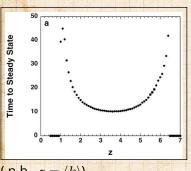






(n.b., $z = \langle k \rangle$)

Largest vulnerable component = critical mass.





Two phase transitions.

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Largest vulnerable component = critical mass.

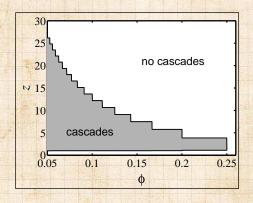


Now have endogenous mechanism for spreading from an individual to the critical mass and then beyond.





Cascade window for random networks



(n.b.,
$$z = \langle k \rangle$$
)

Outline of cascade window for random networks.

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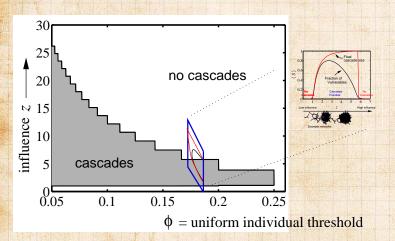








Cascade window for random networks



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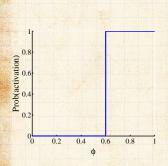
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Assumes deterministic response functions

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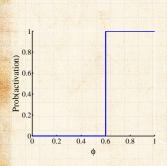
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Assumes deterministic response functions



 $\Leftrightarrow \phi_* = \text{threshold of an}$ individual.

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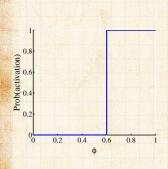
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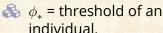








Assumes deterministic response functions



 $\Leftrightarrow f(\phi_*) = distribution of$ thresholds in a population.

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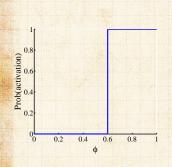
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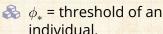


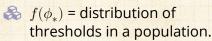


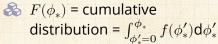




Assumes deterministic response functions







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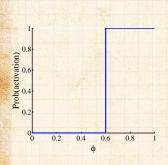
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- Assumes deterministic response functions
- $\Leftrightarrow \phi_* = \text{threshold of an}$ individual.
- $\Leftrightarrow f(\phi_*) = distribution of$ thresholds in a population.
- $\Re F(\phi_*)$ = cumulative distribution = $\int_{\phi'=0}^{\phi_*} f(\phi'_*) d\phi'_*$
- $\Leftrightarrow \phi_t$ = fraction of people 'rioting' at time step t.

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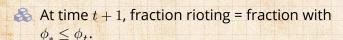
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 \gg iterative maps in the unit interval



 $\phi_* \leq \phi_+$.



$$\phi_{t+1} = \int_0^{\phi_t} f(\phi_*) \mathrm{d}\phi_* = F(\phi_*)|_0^{\phi_t} = F(\phi_t)$$

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 $\phi_{\star} \leq \phi_{\star}$.



$$\phi_{t+1} = \int_0^{\phi_t} f(\phi_*) \mathrm{d}\phi_* = F(\phi_*)|_0^{\phi_t} = F(\phi_t)$$

 \Longrightarrow | sterative maps of the unit interval [0, 1].

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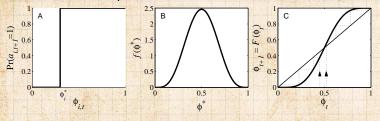
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Action based on perceived behavior of others.





Two states: S and I



Recover now possible (SIS)



 ϕ = fraction of contacts 'on' (e.g., rioting)

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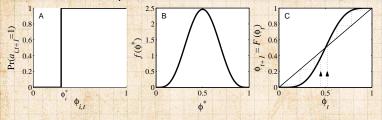


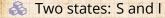


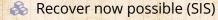


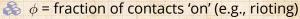


Action based on perceived behavior of others.









Discrete time, synchronous update (strong assumption!)

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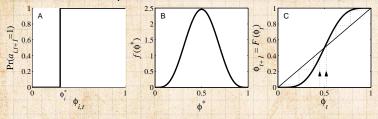
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Action based on perceived behavior of others.



- 🙈 Two states: S and I
- Recover now possible (SIS)
- $\Leftrightarrow \phi$ = fraction of contacts 'on' (e.g., rioting)
- Discrete time, synchronous update (strong assumption!)
- This is a Critical mass model

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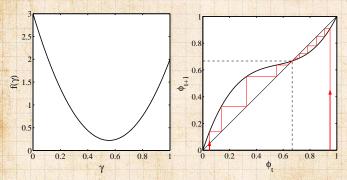
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Example of single stable state model

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Implications for collective action theory:

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Implications for collective action theory:

- 1. Collective uniformity ⇒ individual uniformity

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Implications for collective action theory:

- 1. Collective uniformity ⇒ individual uniformity
- 2. Small individual changes ⇒ large global changes

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- 1. Collective uniformity ⇒ individual uniformity
- 2. Small individual changes ⇒ large global changes

Next:

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- 1. Collective uniformity ⇒ individual uniformity
- 2. Small individual changes ⇒ large global changes

Next:



Connect mean-field model to network model.

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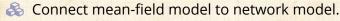


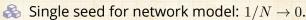


Implications for collective action theory:

- 1. Collective uniformity ⇒ individual uniformity
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Next:





Comparison between network and mean-field model sensible for vanishing seed size for the latter.

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- 1. Collective uniformity ⇒ individual uniformity
- 2. Small individual changes ⇒ large global changes

Next:

- 🗞 Connect mean-field model to network model.
- Single seed for network model: $1/N \rightarrow 0$.
- Comparison between network and mean-field model sensible for vanishing seed size for the latter.

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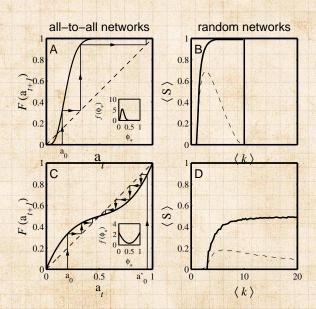
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All-to-all versus random networks



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Spreadworthiness: Cat videos

Bowling with Ragdolls:

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https://www.youtube.com/v/XX-g2nmqL9Q?rel=0



Organic extreme outlier?



Success did not spread to other videos.



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Threshold contagion on random networks

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Three key pieces to describe analytically:

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Three key pieces to describe analytically:

- 1. The fractional size of the largest subcomponent of vulnerable nodes, S_{vuln} .

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Three key pieces to describe analytically:

- 1. The fractional size of the largest subcomponent of vulnerable nodes, S_{vuln} .
- 2. The chance of starting a global spreading event, $P_{\rm trig} = S_{\rm trig}$.
- 3. The expected final size of any successful spread,

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Three key pieces to describe analytically:

- 1. The fractional size of the largest subcomponent of vulnerable nodes, $S_{\rm vuln}$.
- 2. The chance of starting a global spreading event, $P_{\rm trig} = S_{\rm trig}$.
- 3. The expected final size of any successful spread, *S*.
 - n.b., the distribution of *S* is almost always bimodal.

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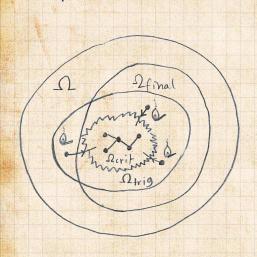
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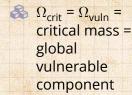
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Example random network structure:





- $\Re \Omega_{\text{trig}} =$ triggering component
- $\Omega_{\text{final}} =$ potential extent of spread
- Ω = entire network

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First goal: Find the largest component of vulnerable nodes.

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First goal: Find the largest component of vulnerable nodes.

Recall that for finding the giant component's size, we had to solve:

$$F_{\pi}(x) = xF_{P}\left(F_{\rho}(x)\right)$$
 and $F_{\rho}(x) = xF_{R}\left(F_{\rho}(x)\right)$

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We'll find a similar result for the subset of nodes that are vulnerable.

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This is a node-based percolation problem.

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 and $F_{\rho}(x) = xF_{R}\left(F_{\rho}(x)\right)$

- We'll find a similar result for the subset of nodes that are vulnerable.
- This is a node-based percolation problem.
- For a general monotonic threshold distribution $f(\phi)$, a degree k node is vulnerable with probability

$$B_{k1} = \int_0^{1/k} f(\phi) \mathsf{d}\phi \,.$$

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We now have a generating function for the probability that a randomly chosen node is vulnerable and has degree k:

$$F_P^{(\mathrm{vuln})}(x) = \sum_{k=0}^\infty P_k B_{k1} x^k.$$

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The generating function for friends-of-friends distribution is similar to before:

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$$F_R^{(\text{vuln})}(x) = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} B_{k1} x^{k-1} = \frac{\frac{\mathrm{d}}{\mathrm{d}x} F_P^{(\text{vuln})}(x)}{\frac{\mathrm{d}}{\mathrm{d}x} F_P(x)|_{x=1}} = \frac{\frac{\mathrm{d}}{\mathrm{d}x} F_P^{(\text{vuln})}(x)}{F_R(x)|_{x=1}} = \frac{\frac{\mathrm{d}}{\mathrm{d}x} F_P^{(\text{vuln})}(x)}{F_R(x)|_{x=1}} = \frac{\mathrm{d}x}{\mathrm{d}x} F_P^{(\text{vuln})}(x)$$



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Note that we still have the underlying degree distribution involved in the denominator.

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Functional relations for component size g.f.'s are almost the same ...

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Functional relations for component size g.f.'s are almost the same ...

$$F_{\pi}^{(\text{vuln})}(x) =$$

$$xF_P^{(\text{vuln})}\left(F_{\rho}^{(\text{vuln})}(x)\right)$$

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Functional relations for component size g.f.'s are almost the same ...

$$F_{\pi}^{(\text{vuln})}(x) = \underbrace{1 - F_{P}^{(\text{vuln})}(1)}_{\substack{\text{central node} \\ \text{is not} \\ \text{vulnerable}}} + x F_{P}^{(\text{vuln})} \left(F_{\rho}^{(\text{vuln})}(x) \right)$$

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$$F_{\rho}^{(\text{vuln})}(x) = x F_{R}^{(\text{vuln})} \left(F_{\rho}^{(\text{vuln})}(x) \right)$$

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$$F_{\rho}^{(\text{vuln})}(x) = \underbrace{1 - F_{R}^{(\text{vuln})}(1)}_{\begin{subarray}{c} \text{first node} \\ \text{is not} \\ \text{vulnerable} \end{subarray}}^{(\text{vuln})}(x) + x F_{R}^{(\text{vuln})}\left(F_{\rho}^{(\text{vuln})}(x)\right)$$

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Can now solve as before to find

$$S_{\text{vuln}} = 1 - F_{\pi}^{(\text{vuln})}(1).$$

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Second goal: Find probability of triggering largest vulnerable component.

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Second goal: Find probability of triggering largest vulnerable component.

Assumption is first node is randomly chosen.

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- Second goal: Find probability of triggering largest vulnerable component.
- Assumption is first node is randomly chosen.
- Same set up as for vulnerable component except now we don't care if the initial node is vulnerable or not:

$$\begin{split} F_{\pi}^{(\mathrm{trig})}(x) &= x \textcolor{red}{F_{P}} \left(F_{\rho}^{(\mathrm{vuln})}(x) \right) \\ F_{\rho}^{(\mathrm{vuln})}(x) &= 1 - F_{R}^{(\mathrm{vuln})}(1) + x F_{R}^{(\mathrm{vuln})} \left(F_{\rho}^{(\mathrm{vuln})}(x) \right) \end{split}$$

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Solve as before to find $P_{\text{trig}} = S_{\text{trig}} = 1 - F_{\pi}^{(\text{trig})}(1)$.

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Possibility: binary indicator of phase. Global spreading events are either possible or can never happen.

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Possibility: binary indicator of phase. Global spreading events are either possible or can never happen.



For random networks, global spreading possibility is understood as meaning a giant component of vulnerable nodes exists.

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- Possibility: binary indicator of phase. Global spreading events are either possible or can never happen.
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- Next: what's the probability that a randomly infected node will cause a global spreading event?

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- & Call this P_{trig} .

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- As usual, it's all about edges and we need to first determine the probability that an infected edge leads to a global spreading event.

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- As usual, it's all about edges and we need to first determine the probability that an infected edge leads to a global spreading event.
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- Later: Generalize to more complex networks involving assortativity of all kinds.

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Probability an infected edge leads to a global spreading event:



 Q_{trig} must satisfying a one-step recursion relation.

$$Q_{\mathrm{trig}} = \sum_{k,k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k-1} \right].$$

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Probability an infected edge leads to a global spreading event:



 Q_{trig} must satisfying a one-step recursion relation.



Follow an infected edge and use three pieces:

$$Q_{\mathrm{trig}} = \sum_{k,k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k-1}\right].$$

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 Q_{trig} must satisfying a one-step recursion relation.



Follow an infected edge and use three pieces:

- 1. Probability of reaching a degree k node is $Q_k = \frac{k P_k}{\langle k \rangle}$.

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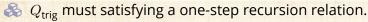
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Probability an infected edge leads to a global spreading event:



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$$Q_{\mathrm{trig}} = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k-1}\right].$$

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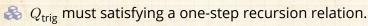
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Put everything together and solve for Q_{trig}

$$Q_{\mathrm{trig}} = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k-1}\right].$$

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& Global spreading is possible if the fractional size S_{vuln} of the largest component of vulnerables is "giant".

$$S_{\mathrm{vuin}} = \sum_{k} P_{k} \bullet B_{k1} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k} \right] > 0.$$

$$P_{\mathrm{trig}} = S_{\mathrm{trig}} = \sum_{k} P_{k} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k}\right]$$



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Interpret S_{yuln} as the probability a randomly chosen node is vulnerable and that infecting it leads to a global spreading event:

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$$P_{\mathrm{trig}} = S_{\mathrm{trig}} = \sum_{k} P_{k} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k}\right]$$



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- \Leftrightarrow Amounts to having $Q_{\text{trig}} > 0$.
- Probability of global spreading differs only in that we don't care if the initial seed is vulnerable or not:

$$P_{\mathrm{trig}} = S_{\mathrm{trig}} = \sum_{k} P_{k} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k} \right]$$

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- $\red {A}$ Amounts to having $Q_{\rm trig} > 0$.
- Probability of global spreading differs only in that we don't care if the initial seed is vulnerable or not:

$$P_{\mathrm{trig}} = S_{\mathrm{trig}} = \sum_{k} P_{k} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k} \right]$$

& As for S_{vuln} , P_{trig} is non-zero when $Q_{\text{trig}} > 0$.



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 $\red{8}$ We found that $F_{\rho}^{(\text{vuln})}(1)$ —the probability that a random edge leads to a finite vulnerable component—satisfies

$$F_{\rho}^{(\mathrm{vuln})}(1) = 1 - F_{R}^{(\mathrm{vuln})}(1) + 1 \cdot F_{R}^{(\mathrm{vuln})} \left(F_{\rho}^{(\mathrm{vuln})}(1) \right).$$

We set
$$F_{\rho}^{(\mathrm{vuln})}(1) = 1 - Q_{\mathrm{trig}}$$
 and deploy $F_{R}^{(\mathrm{vuln})}(x) = \sum_{k=0}^{\infty} \frac{kP_{k}}{|k|} B_{k1} x^{k-1}$ to find

$$Q_{\mathrm{trig}} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - \left(1 - Q_{\mathrm{trig}} \right)^{k-1} \right].$$

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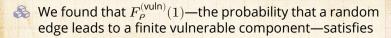
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We set $F_{
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$$1 - Q_{\rm trig} = 1 - \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} B_{k1} + \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} B_{k1} \left(1 - Q_{\rm trig} \right)^k$$

$$Q_{\text{trig}} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - \left(1 - Q_{\text{trig}} \right)^{k-1} \right].$$

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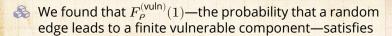
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$$F_{\rho}^{(\mathrm{vuln})}(1) = 1 - F_{R}^{(\mathrm{vuln})}(1) + 1 \cdot F_{R}^{(\mathrm{vuln})} \left(F_{\rho}^{(\mathrm{vuln})}(1) \right).$$

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$$Q_{\mathrm{trig}} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - \left(1 - Q_{\mathrm{trig}}\right)^{k-1}\right],$$

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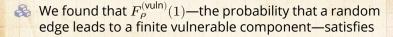
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$$F_{\rho}^{(\mathrm{vuln})}(1) = 1 - F_{R}^{(\mathrm{vuln})}(1) + 1 \cdot F_{R}^{(\mathrm{vuln})} \left(F_{\rho}^{(\mathrm{vuln})}(1) \right).$$

$$1 - Q_{\rm trig} = 1 - \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} B_{k1} + \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} B_{k1} \left(1 - Q_{\rm trig} \right)^{k-1}.$$

Some breathless algebra it all matches:

$$Q_{\mathrm{trig}} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - \left(1 - Q_{\mathrm{trig}} \right)^{k-1} \right].$$

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Fractional size of the largest vulnerable component:



The generating function approach gave $S_{\text{yuln}} = 1 - F_{\pi}^{(\text{vuln})}(1)$ where

$$F_\pi^{(\mathrm{vuln})}(1) = 1 - F_P^{(\mathrm{vuln})}(1) + 1 \cdot F_P^{(\mathrm{vuln})}\left(F_\rho^{(\mathrm{vuln})}(1)\right).$$

$$1 - S_{\text{vuln}} = 1 - \sum_{k=0}^{\infty} P_k B_{k1} + \sum_{k=0}^{\infty} P_k B_{k1} \left(1 - Q_{\text{trig}} \right)^k$$

$$S_{\text{vuln}} = \sum_{k=0}^{\infty} P_k B_{k1} \left[1 + \left(1 - Q_{\text{trig}} \right)^k \right]$$

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$$\label{eq:power_power} \begin{split} & \text{Again using } F_{\rho}^{(\text{vuln})}(1) = 1 - Q_{\text{trig}} \text{ along with} \\ & F_{P}^{(\text{vuln})}(x) = \sum_{k=0}^{\infty} P_k B_{k1} x^k \text{, we have:} \end{split}$$

$$1 - S_{\mathrm{vuln}} = 1 - \sum_{k=0}^{\infty} P_k B_{k1} + \sum_{k=0}^{\infty} P_k B_{k1} \left(1 - Q_{\mathrm{trig}}\right)^k. \label{eq:spectrum}$$

Excited scrabbling about gives us, as before:

$$S_{\mathsf{vuln}}
otin \sum_{k=0}^{\infty} P_k B_{k1} \left[1 - \left(1 - Q_{\mathsf{trig}} \right)^k \right]$$

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$$S_{\mathrm{vuln}} = \sum_{k=0}^{\infty} P_k B_{k1} \left[1 - \left(1 - Q_{\mathrm{trig}} \right)^k \right]. \label{eq:svuln}$$

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Slight adjustment to the vulnerable component calculation.

 $S_{
m trig} = 1 - F_{\pi}^{
m (trig)}(1)$ where

$$F_{\pi}^{(\mathrm{trig})}(1) = 1 \cdot F_{P}\left(F_{\rho}^{(\mathrm{vuln})}(1)\right)$$

We play these cards: $F_{\rho}^{(\mathrm{vuln})}(1)=1-Q_{\mathrm{trig}}$ and $F_{P}(x)=\sum_{k=0}^{\infty}P_{k}x^{k}$ to arrive at

$$1 - S_{\mathsf{trig}} = 1 + \sum_{k=0}^{\infty} P_k \left(1 - Q_{\mathsf{trig}}\right)^k$$

More scruffing around brings happiness

$$S_{\mathrm{riig}}^{\mathrm{riig}} = \sum_{k=0}^{\infty} P_k \left[1 - \left(1 + Q_{\mathrm{riig}} \right)^k \right].$$

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- Slight adjustment to the vulnerable component calculation.
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$$S_{\text{trig}} + \sum_{k=0}^{\infty} P_k \left[1 - \left(1 - Q_{\text{trig}} \right)^k \right],$$

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More scruffing around brings happiness:

$$S_{\rm trig} = \sum_{k=0}^{\infty} P_k \left[1 - \left(1 - Q_{\rm trig} \right)^k \right]. \label{eq:Strig}$$

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Earlier, we showed the global spreading condition follows from the gain ratio $\mathbb{R} > 1$:

$$\mathbf{R} = \sum_{k=0}^{\infty} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} > 1.$$

$$Q_{\mathrm{trig}} = \sum_k \frac{k P_k}{\langle k \rangle} \bullet B_{kT} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k-1}\right].$$

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- $lap{8}$ We would very much like to see that ${f R}>1$ matches up with $Q_{\rm trig}>0$.
 - It really would be just so totally awesome.
 - Must come from our basic edge triggering probability equation:

$$Q_{\mathrm{trig}} = \sum_k \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - (1 - Q_{\mathrm{trig}})^{k-1} \right] \,.$$

- When does this equation have a solution $0 < Q_{\mathrm{trig}} \leq 1$?
- We need to find out what happens as $Q_{\rm trig}
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When does this equation have a solution $0 < Q_{\mathrm{trig}} \leq 1$?

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 ightarrow 0.^{[9]}$

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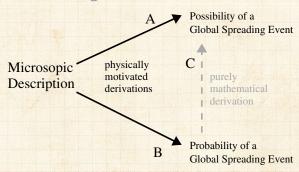
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What we're doing:



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 \Longrightarrow For $Q_{\text{trig}} \to 0^+$, equation tends towards

$$Q_{\mathrm{trig}} = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - \left(1 - (k-1) Q_{\mathrm{trig}} + \ldots \right) \right]$$

$$\Rightarrow Q_{\rm trig} = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet (k-1) Q_{\rm trig}$$

$$\Rightarrow 1 = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1}$$

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$$Q_{\mathrm{trig}} = \sum_{k} \frac{kP_{k}}{\langle k \rangle} \bullet B_{k1} \bullet \left[\cancel{1} + \left(\cancel{1} + (k-1)Q_{\mathrm{trig}} + \ldots \right) \right]$$

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$$\begin{split} Q_{\mathrm{trig}} &= \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet B_{k1} \bullet \left[\cancel{1} + \left(\cancel{1} + (k-1)Q_{\mathrm{trig}} + \ldots \right) \right] \\ \\ &\Rightarrow Q_{\mathrm{trig}} = \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet B_{k1} \bullet (k-1)Q_{\mathrm{trig}} \\ \\ &\Rightarrow 1 = \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} \end{split}$$

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$$\begin{split} Q_{\mathrm{trig}} &= \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet B_{k1} \bullet \left[\cancel{1} + \left(\cancel{1} + (k-1)Q_{\mathrm{trig}} + \ldots \right) \right] \\ \\ &\Rightarrow Q_{\mathrm{trig}} = \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet B_{k1} \bullet (k-1)Q_{\mathrm{trig}} \\ \\ &\Rightarrow 1 = \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} \end{split}$$

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3 Only defines the phase transition points (i.e., $\mathbf{R} = 1$).



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Only defines the phase transition points (i.e., $\mathbf{R} = 1$).



Inequality?

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$$Q_{\mathrm{trig}} = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[1 - \left(1 - (k-1)Q_{\mathrm{trig}} + {k-1 \choose 2}Q_{\mathrm{trig}}^2\right) \right]$$

$$\begin{split} &\Rightarrow Q_{\mathsf{trig}} = \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet B_{k1} \bullet \left[(k-1) Q_{\mathsf{trig}} - {k-1 \choose 2} Q_{\mathsf{trig}}^2 \right] \\ &\Rightarrow \sum_{k} \frac{k P_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} = 1 + \sum_{k} \frac{k P_k}{\langle k \rangle} B_{k1} {k-1 \choose 2} Q_{\mathsf{trig}} \end{split}$$

We have
$$Q_{\mathrm{trig}} > 0$$
 if $\sum_k \frac{kP_k}{(k)} \bullet (k-1) \bullet B_{k1} > 1$.

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- & We have $Q_{\mathsf{trig}} > 0$ if $\sum_k \frac{kP_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} > 1$.
- Repeat: Above is a mathematical connection between two physically derived equations.

From this connection, we don't know anything about a gain ratio R or how to arrange the pieces.

& Again take $Q_{\mathsf{trig}} \to 0^+$, but keep next higher order term:

$$\begin{split} Q_{\mathrm{trig}} &= \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet B_{k1} \bullet \left[\cancel{1} + \left(\cancel{1} + (k-1)Q_{\mathrm{trig}} - \binom{k-1}{2} Q_{\mathrm{trig}}^{2} \right) \right] \\ &\Rightarrow Q_{\mathrm{trig}} = \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet B_{k1} \bullet \left[(k-1)Q_{\mathrm{trig}} - \binom{k-1}{2} Q_{\mathrm{trig}}^{2} \right] \\ &\Rightarrow \sum_{k} \frac{k P_{k}}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} = 1 + \sum_{k} \frac{k P_{k}}{\langle k \rangle} B_{k1} \binom{k-1}{2} Q_{\mathrm{trig}} \end{split}$$

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Third goal: Find expected fractional size of spread.

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Third goal: Find expected fractional size of spread. Not obvious even for uniform threshold problem.

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Third goal: Find expected fractional size of spread. Not obvious even for uniform threshold problem.



Difficulty is in figuring out if and when nodes that need > 2 hits switch on.

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COCONUTS

Third goal: Find expected fractional size of spread.

Not obvious even for uniform threshold problem.

Difficulty is in figuring out if and when nodes that need > 2 hits switch on.

Problem solved for infinite seed case by Gleeson and Cahalane:

"Seed size strongly affects cascades on random networks," Phys. Rev. E, 2007. [7]

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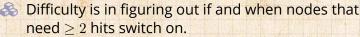


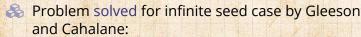


Third goal: Find expected fractional size of spread.

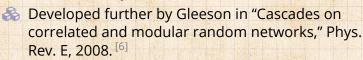


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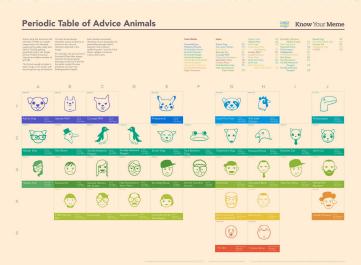
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Meme species:





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Randomly turn on a fraction ϕ_0 of nodes at time t=0

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Randomly turn on a fraction ϕ_0 of nodes at time t=0



Capitalize on local branching network structure of random networks (again)

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Randomly turn on a fraction ϕ_0 of nodes at time t=0



Capitalize on local branching network structure of random networks (again)



Now think about what must happen for a specific node i to become active at time t:

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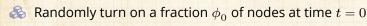
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- Capitalize on local branching network structure of random networks (again)
- Now think about what must happen for a specific node *i* to become active at time *t*:
 - t=0: i is one of the seeds (prob = ϕ_0)
 - t=1, i was not a seed but enough of i's friends switched on at time t=0 so that i's threshold is now exceeded.
 - t = 2: enough of i's friends and friends-of-friends switched on at time t = 0 so that i's threshold is now exceeded.
 - t = n enough nodes within n hops of i switched on at t = 0 and their effects have propagated to reach i.

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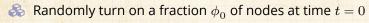
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Idea:



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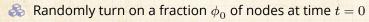
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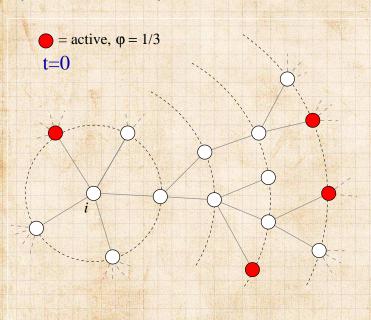
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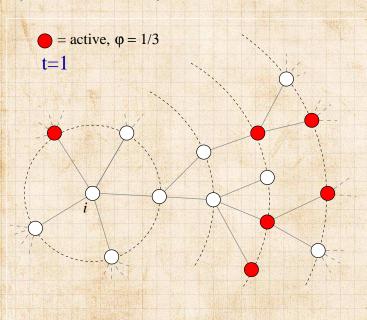
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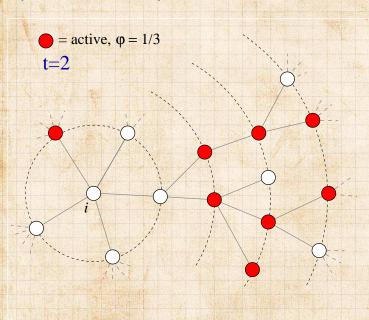
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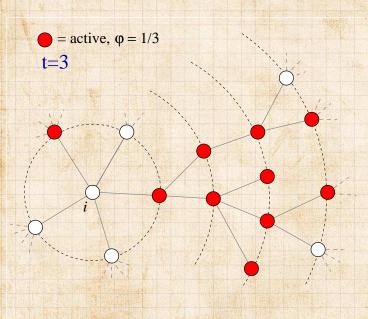
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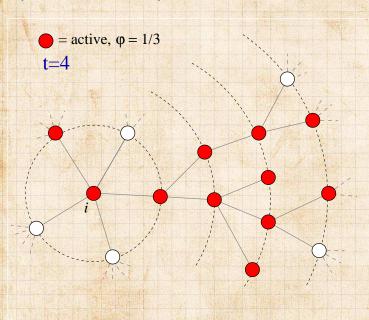
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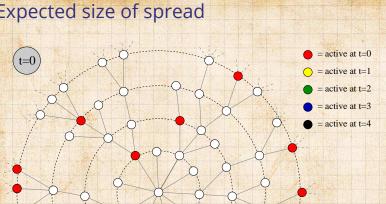
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 $\phi = 1/3$



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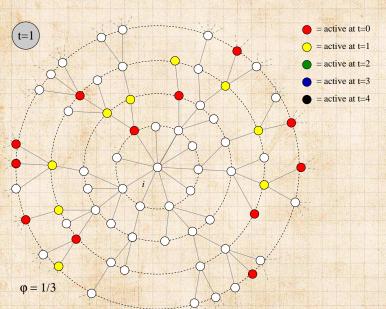












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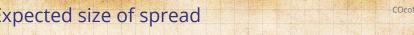
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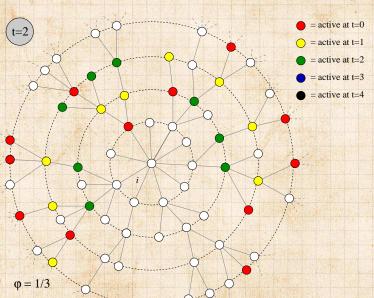
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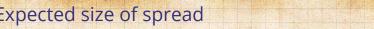
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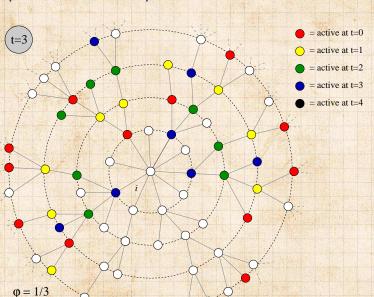
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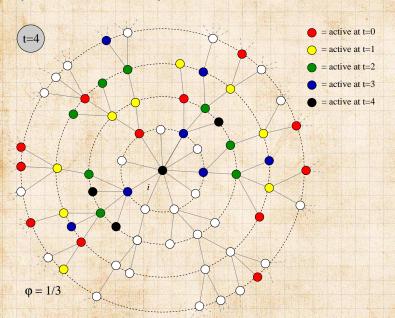












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Calculations presume nodes do not become inactive (strong restriction, liftable)

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Calculations presume nodes do not become inactive (strong restriction, liftable)



Not just for threshold model—works for a wide range of contagion processes.

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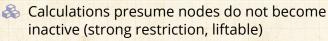
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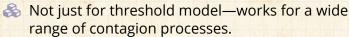
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We can analytically determine the entire time evolution, not just the final size.

Pr(node of degree k switches on at time t). Even more, we can compute: Pr(specific node switches on at time t).

Asynchronous updating can be handled too

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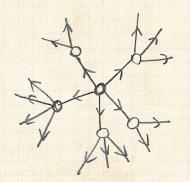
Spreading possibility Spreading probability Physical explanation Final size

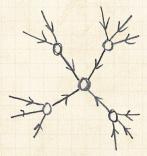




Pleasantness:

Taking off from a single seed story is about expansion away from a node.





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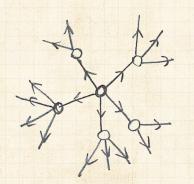


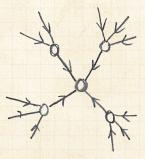




Pleasantness:

- Taking off from a single seed story is about expansion away from a node.
- Extent of spreading story is about contraction at a node.





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Notation:

 $\phi_{k,t} = \mathbf{Pr}(\mathsf{a} \mathsf{ degree} \; k \mathsf{ node} \mathsf{ is} \mathsf{ active} \mathsf{ at} \mathsf{ time} \; t).$



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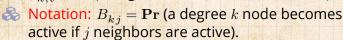


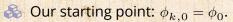




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Notation: $B_{kj} = \mathbf{Pr}$ (a degree k node becomes active if *i* neighbors are active).

 \bigotimes Our starting point: $\phi_{k,0} = \phi_0$.

 $\bigotimes_{i} {k \choose j} \phi_0^j (1 - \phi_0)^{k-j} = \mathbf{Pr} (j \text{ of a degree } k \text{ node's})$ neighbors were seeded at time t=0).

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 $\phi_{k,t} = \mathbf{Pr}(\text{a degree } k \text{ node is active at time } t).$

Notation: $B_{kj} = \mathbf{Pr}$ (a degree k node becomes active if j neighbors are active).

 \bigotimes Our starting point: $\phi_{k,0} = \phi_0$.

 $\bigotimes_{i} {k \choose j} \phi_0^j (1 - \phi_0)^{k-j} = \mathbf{Pr} (j \text{ of a degree } k \text{ node's})$ neighbors were seeded at time t=0).

 \mathbb{R} Probability a degree k node was a seed at t=0 is ϕ_0 (as above).

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Notation:

 $\phi_{k,t} = \mathbf{Pr}(\mathsf{a} \mathsf{ degree} \; k \mathsf{ node} \mathsf{ is} \mathsf{ active} \mathsf{ at} \mathsf{ time} \; t).$

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 $\red {\begin{tabular}{l} \begin{tabular}{l} \begin$

 $(k) \phi_0^j (1 - \phi_0)^{k-j} = \mathbf{Pr} (j \text{ of a degree } k \text{ node's neighbors were seeded at time } t = 0).$

Probability a degree k node was a seed at t = 0 is ϕ_0 (as above).

Probability a degree k node was not a seed at t=0 is $(1-\phi_0)$.

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Notation:

 $\phi_{k,t} = \mathbf{Pr}(\mathsf{a} \mathsf{ degree} \; k \mathsf{ node} \mathsf{ is} \mathsf{ active} \mathsf{ at} \mathsf{ time} \; t).$

- Notation: $B_{kj} = \mathbf{Pr}$ (a degree k node becomes active if j neighbors are active).
- \Leftrightarrow Our starting point: $\phi_{k,0} = \phi_0$.
- $(k)^{j} \phi_0^{j} (1 \phi_0)^{k-j} = \mathbf{Pr} (j \text{ of a degree } k \text{ node's neighbors were seeded at time } t = 0).$
- Probability a degree k node was a seed at t = 0 is ϕ_0 (as above).
- Probability a degree k node was not a seed at t=0 is $(1-\phi_0)$.
- Combining everything, we have:

$$\phi_{k,1} = \frac{\phi_0}{\phi_0} + (1 - \phi_0) \sum_{j=0}^k {k \choose j} \phi_0^{\,j} (1 - \phi_0)^{k-j} B_{kj}.$$

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For general t, we need to know the probability an edge coming into a degree k node at time t is active.

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For general t, we need to know the probability an edge coming into a degree k node at time t is active.

 \triangle Notation: call this probability θ_{\star} .

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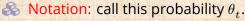
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For general t, we need to know the probability an edge coming into a degree k node at time t is active.



 \Leftrightarrow We already know $\theta_0 = \phi_0$.

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For general t, we need to know the probability an edge coming into a degree k node at time t is active.

 \mathbb{A} Notation: call this probability θ_t .

 \clubsuit We already know $\theta_0 = \phi_0$.

3 Story analogous to t=1 case. For specific node i:

$$\phi_{i,t+1} = \phi_0 + (1 - \phi_0) \sum_{j=0}^{k_i} {k_i \choose j} \theta_t^{\,j} (1 - \theta_t)^{k_i - j} B_{k_i j}.$$

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 $\red Notation:$ call this probability θ_t .

 $\red {8}$ We already know $heta_0 = \phi_0$.

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Average over all nodes with degree k to obtain expression for ϕ_{t+1} :

$$\phi_{t+1} = \frac{\phi_0}{\phi_0} + (1 - \phi_0) \sum_{k=0}^{\infty} P_k \sum_{j=0}^k {k \choose j} \theta_t^{\ j} (1 - \theta_t)^{k-j} B_{kj}.$$

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 \triangle Notation: call this probability θ_{+} .

3 Story analogous to t=1 case. For specific node i:

$$\phi_{i,t+1} = \phi_0 + (1 - \phi_0) \sum_{j=0}^{k_i} {k_i \choose j} \theta_t^j (1 - \theta_t)^{k_i - j} B_{k_i j}.$$

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For general t, we need to know the probability an edge coming into a degree k node at time t is active.

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 $\red {8}$ We already know $heta_0 = \phi_0$.

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Average over all nodes with degree k to obtain expression for ϕ_{t+1} :

$$\phi_{t+1} = \frac{\phi_0}{\phi_0} + (1 - \phi_0) \sum_{k=0}^{\infty} P_k \sum_{j=0}^k {k \choose j} \theta_t^{\ j} (1 - \theta_t)^{k-j} B_{kj}.$$

& So we need to compute θ_t ... massive excitement...

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$$\theta_1 = \phi_0 +$$

$$(1-\phi_0) \sum_{k=1}^{\infty} \frac{k P_k}{\langle k \rangle} \sum_{j=0}^{k-1} {k-1 \choose j} \theta_0^{\ j} (1-\theta_0)^{k-1-j} B_{kj}$$

- $\frac{kP_k}{\langle k \rangle} = Q_k = \mathbf{Pr}$ (edge connects to a degree k node).
- $\sum_{j=0}^{k-1}$ piece gives \mathbf{Pr} (degree node k activates if j of its k-1 incoming neighbors are active).
- $\ \phi_0$ and $(1-\phi_0)$ terms account for state of node at time t=0.
 - See this all generalizes to give θ_{+-1} in terms of θ_{+} ...

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$$\theta_1 = \phi_0 +$$

$$(1-\phi_0)\sum_{k=1}^{\infty}\frac{kP_k}{\langle k\rangle}\sum_{j=0}^{k-1}{k-1\choose j}\theta_0^{\ j}(1-\theta_0)^{k-1-j}B_{kj}$$

- $\frac{kP_k}{\langle k \rangle} = Q_k = \mathbf{Pr}$ (edge connects to a degree k node).
- $\underset{i=0}{\&} \sum_{j=0}^{k-1}$ piece gives **Pr** (degree node k activates if jof its k-1 incoming neighbors are active).
- $\Leftrightarrow \phi_0$ and $(1-\phi_0)$ terms account for state of node at time t=0.
- \Leftrightarrow See this all generalizes to give θ_{t+1} in terms of θ_t ...

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Two pieces: edges first, and then nodes

1.
$$\theta_{t+1} = \underbrace{\phi_0}_{\text{exogenous}}$$

$$+(1-\phi_0)\underbrace{\sum_{k=1}^{\infty}\frac{kP_k}{\langle k\rangle}\sum_{j=0}^{k-1}{k-1\choose j}\theta_t^{\ j}(1-\theta_t)^{k-1-j}B_{kj}}_{\text{social effects}}$$

with $\theta_0 = \phi_0$.

2.
$$\phi_{t+1} =$$

$$\underbrace{\frac{\phi_0}{\exp \text{exogenous}}}_{\text{exogenous}} + (1 - \phi_0) \underbrace{\sum_{k=0}^{\infty} P_k \sum_{j=0}^{k} \binom{k}{j} \theta_t^{\,j} (1 - \theta_t)^{k-j} B_{kj}}_{\text{social effects}}.$$

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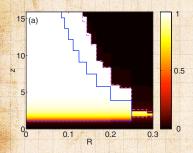
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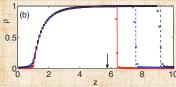






Comparison between theory and simulations





From Gleeson and Cahalane [7]



Pure random networks with simple threshold responses



R = uniform threshold(our ϕ_*); z = averagedegree; $\rho = \phi$; $q = \theta$; $N = 10^5$.



 $\phi_0 = 10^{-3}, 0.5 \times 10^{-2},$ and 10^{-2} .



Cascade window is for $\phi_0 = 10^{-2}$ case.



Sensible expansion of cascade window as ϕ_0 increases.

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Retrieve cascade condition for spreading from a single seed in limit $\phi_0 \to 0$.

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Retrieve cascade condition for spreading from a single seed in limit $\phi_0 \to 0$.

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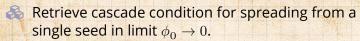
Spreading possibility Spreading probability Physical explanation

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 $\red {\mathbb R}$ Depends on map $heta_{t+1} = G(heta_t;\phi_0)$.

First: if self-starters are present, some activation is assured:

$$G(0; \phi_0) = \sum_{k=1}^{\infty} \frac{kP_k}{\langle k \rangle} \bullet B_{k0} > 0.$$

meaning $B_{k0} > 0$ for at least one value of $k \ge 1$.

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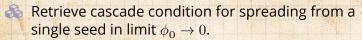
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meaning $B_{k0} > 0$ for at least one value of $k \ge 1$.

All If $\theta=0$ is a fixed point of G (i.e., $G(0;\phi_0)=0$) then spreading occurs for a small seed if

$$G'(0;\phi_0) = \sum_{k=0}^{\infty} \frac{kP_k}{\langle k \rangle} \bullet (k-1) \bullet B_{k1} > 1.$$

Insert question from assignment 10 🗹

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In words:



A If $G(0; \phi_0) > 0$, spreading must occur because some nodes turn on for free.

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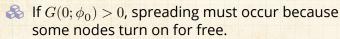
Final size







In words:



A If G has an unstable fixed point at $\theta = 0$, then cascades are also always possible.

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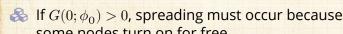
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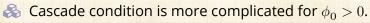
In words:



some nodes turn on for free. A If G has an unstable fixed point at $\theta = 0$, then

cascades are also always possible.

Non-vanishing seed case:



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In words:

- A If $G(0; \phi_0) > 0$, spreading must occur because some nodes turn on for free.
- A If G has an unstable fixed point at $\theta = 0$, then cascades are also always possible.

Non-vanishing seed case:

- Cascade condition is more complicated for $\phi_0 > 0$.
- A If G has a stable fixed point at $\theta = 0$, and an unstable fixed point for some $0 < \theta_* < 1$, then for $\theta_0 > \theta_*$, spreading takes off.

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In words:

- If $G(0; \phi_0) > 0$, spreading must occur because some nodes turn on for free.
- \Re If G has an unstable fixed point at $\theta=0$, then cascades are also always possible.

Non-vanishing seed case:

- $\red {\Bbb S}$ Cascade condition is more complicated for $\phi_0>0$.
- If G has a stable fixed point at $\theta=0$, and an unstable fixed point for some $0<\theta_*<1$, then for $\theta_0>\theta_*$, spreading takes off.
- \Leftrightarrow Tricky point: G depends on ϕ_0 , so as we change ϕ_0 , we also change G.

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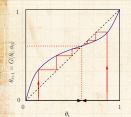
Theory

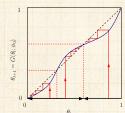
Spreading possibility Spreading probability Physical explanation Final size

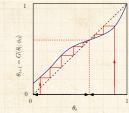














Given $\theta_0 (= \phi_0)$, θ_{∞} will be the nearest stable fixed point, either above or below.

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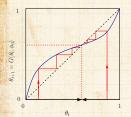
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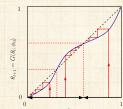


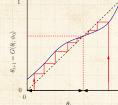














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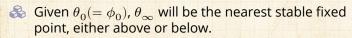
Spreading possibility Spreading probability Physical explanation Final size

References





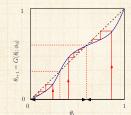


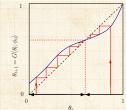


n.b., adjacent fixed points must have opposite stability types.

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- Given $\theta_0 (= \phi_0)$, θ_{∞} will be the nearest stable fixed point, either above or below.
- n.b., adjacent fixed points must have opposite stability types.
- Important: Actual form of G depends on ϕ_0 .

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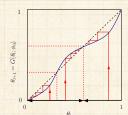
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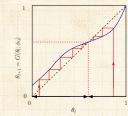












- Given $\theta_0 (= \phi_0)$, θ_{∞} will be the nearest stable fixed point, either above or below.
- n.b., adjacent fixed points must have opposite stability types.
- Important: Actual form of G depends on ϕ_0 .
- \mathbb{A} Important: ϕ_{\star} can only increase monotonically so ϕ_{0} must shape G so that ϕ_0 is at or above an unstable fixed point.

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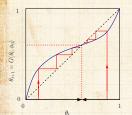
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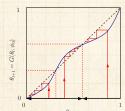
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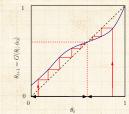












- Given $\theta_0 (= \phi_0)$, θ_{∞} will be the nearest stable fixed point, either above or below.
- n.b., adjacent fixed points must have opposite stability types.
- Important: Actual form of G depends on ϕ_0 .
- A Important: ϕ_{\star} can only increase monotonically so ϕ_{0} must shape G so that ϕ_0 is at or above an unstable fixed point.
- \Leftrightarrow First reason: $\phi_1 \geq \phi_0$.

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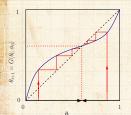
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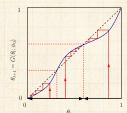
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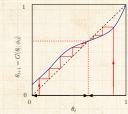












- Given $\theta_0 (= \phi_0)$, θ_∞ will be the nearest stable fixed point, either above or below.
- n.b., adjacent fixed points must have opposite stability types.
- Important: ϕ_t can only increase monotonically so ϕ_0 must shape G so that ϕ_0 is at or above an unstable fixed point.
- \Leftrightarrow First reason: $\phi_1 \ge \phi_0$.
- \Leftrightarrow Second: $G'(\theta; \phi_0) \ge 0, 0 \le \theta \le 1$.

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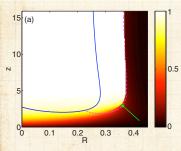
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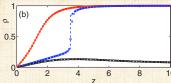
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From Gleeson and Cahalane [7]



Now allow thresholds to be distributed according to a Gaussian with mean R.



R = 0.2, 0.362, and0.38; $\sigma = 0.2$.

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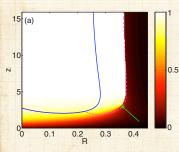
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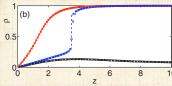
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From Gleeson and Cahalane [7]



Now allow thresholds to be distributed according to a Gaussian with mean R.



R = 0.2, 0.362, and0.38; $\sigma = 0.2$.



 $\phi_0 = 0$ but some nodes have thresholds < 0 so effectively $\phi_0 > 0$.



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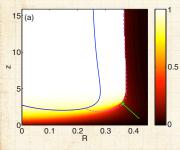
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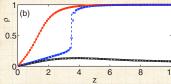






Interesting behavior:





From Gleeson and Cahalane [7]

Now allow thresholds to be distributed according to a Gaussian with mean R.

- R = 0.2, 0.362, and0.38; $\sigma = 0.2$.
- $\phi_0 = 0$ but some nodes have thresholds < 0 so effectively $\phi_0 > 0$.
- Now see a (nasty) discontinuous phase transition for low $\langle k \rangle$.

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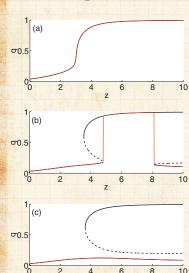
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Interesting behavior:



From Gleeson and Cahalane [7]

Plots of stability points for $\theta_{t+1} = G(\theta_t; \phi_0)$.



n.b.: 0 is not a fixed point here: $\theta_0 = 0$ always takes off.



Top to bottom: R =0.35, 0.371, and 0.375.



Saddle node bifurcations appear and merge (b and c). COCONUTS

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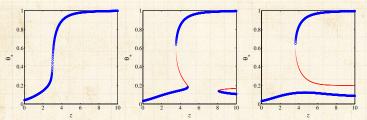
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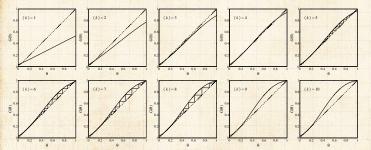




What's happening:



Fixed points slip above and below the $\theta_{t+1} = \theta_t$ line:



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Time-dependent solutions

Synchronous update

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Synchronous update

 \Leftrightarrow Done: Evolution of ϕ_t and θ_t given exactly by the maps we have derived.

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Synchronous update

 \Leftrightarrow Done: Evolution of ϕ_t and θ_t given exactly by the maps we have derived.

Asynchronous updates

& Update nodes with probability α .

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Synchronous update

 \Leftrightarrow Done: Evolution of ϕ_t and θ_t given exactly by the maps we have derived.

Asynchronous updates

- $\red {\mathbb R}$ Update nodes with probability ${\alpha}.$
- As $\alpha \to 0$, updates become effectively independent.

Now can talk about $\phi(t)$ and $\theta(t)$.

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Solid dive into understanding contagion on generalized random networks.

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Much can be generalized for more realistic kinds of networks: degree-correlated, modular, bipartite, ...

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Neural reboot (NR):

Pangolin happiness:

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