

# Measures of centrality

Complex Networks | @networksvox  
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## How big is my node?

**Basic question:** how 'important' are specific nodes and edges in a network?

An important node or edge might:

1. **handle** a relatively large amount of the network's traffic (e.g., cars, information);
2. **bridge** two or more distinct groups (e.g., liason, interpreter);
3. be a **source** of important ideas, knowledge, or judgments (e.g., supreme court decisions, an employee who 'knows where everything is').

So how do we quantify such a slippery concept as importance?

We generate ad hoc, reasonable measures, and examine their utility ...

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## Centrality

One possible reflection of importance is **centrality**.

Presumption is that nodes or edges that are (in some sense) in the middle of a network are important for the network's function.

Idea of centrality comes from social networks literature<sup>[7]</sup>.

Many flavors of centrality ...

1. Many are topological and quasi-dynamical;
2. Some are based on dynamics (e.g., traffic).

We will define and examine a few ...

(Later: see centrality useful in identifying communities in networks.)

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## Centrality

### Degree centrality

Naively estimate importance by **node degree**.<sup>[7]</sup>

**Doh:** assumes linearity  
(If node  $i$  has twice as many friends as node  $j$ , it's twice as important.)

**Doh:** doesn't take in any non-local information.

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## Closeness centrality

- Idea:** Nodes are more central if they can reach other nodes 'easily.'
- Measure average shortest path from a node to all other nodes.
- Define **Closeness Centrality** for node  $i$  as

$$\frac{N - 1}{\sum_{j, j \neq i} (\text{shortest distance from } i \text{ to } j)}.$$

- Range is 0 (no friends) to 1 (single hub).
- Unclear what the exact values of this measure tells us because of its ad-hocness.
- General problem with simple centrality measures: what do they exactly mean?
- Perhaps, at least, we obtain an ordering of nodes in terms of 'importance.'

## Betweenness centrality

- Betweenness centrality** is based on coherence of shortest paths in a network.
- Idea:** If the quickest way between any two nodes on a network disproportionately involves certain nodes, then they are 'important' in terms of global cohesion.
- For each node  $i$ , count how many shortest paths pass through  $i$ .
- In the case of ties, divide counts between paths.
- Call frequency of shortest paths passing through node  $i$  the betweenness of  $i$ ,  $B_i$ .
- Note: Exclude shortest paths between  $i$  and other nodes.
- Note: works for weighted and unweighted networks.

- Consider a network with  $N$  nodes and  $m$  edges (possibly weighted).
- Computational goal:** Find  $\binom{N}{2}$  shortest paths between all pairs of nodes.
- Traditionally use **Floyd-Warshall** algorithm.
- Computation time grows as  $O(N^3)$ .
- See also:
  - Dijkstra's algorithm for finding shortest path between two specific nodes,
  - and Johnson's algorithm which outperforms Floyd-Warshall for sparse networks:  $O(mN + N^2 \log N)$ .

Newman (2001)<sup>[4, 5]</sup> and Brandes (2001)<sup>[1]</sup> independently derive equally fast algorithms that also compute betweenness.

- Computation times grow as:
  - $O(mN)$  for unweighted graphs;
  - and  $O(mN + N^2 \log N)$  for weighted graphs.

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## Shortest path between node $i$ and all others:

- Consider unweighted networks.
- Use **breadth-first search**:
  - Start at node  $i$ , giving it a distance  $d = 0$  from itself.
  - Create a list of all of  $i$ 's neighbors and label them being at a distance  $d = 1$ .
  - Go through list of most recently visited nodes and find all of their neighbors.
  - Exclude any nodes already assigned a distance.
  - Increment distance  $d$  by 1.
  - Label newly reached nodes as being at distance  $d$ .
  - Repeat steps 3 through 6 until all nodes are visited.

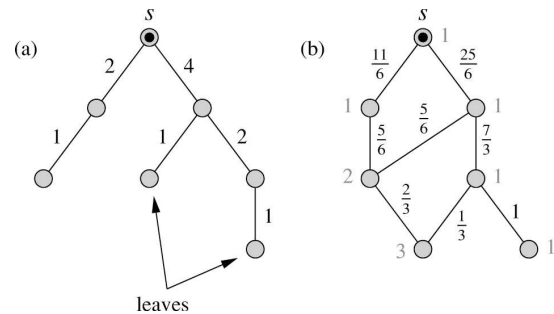
Record which nodes link to which nodes moving out from  $i$  (former are 'predecessors' with respect to  $i$ 's shortest path structure).

Runs in  $O(m)$  time and gives  $N - 1$  shortest paths.

Find all shortest paths in  $O(mN)$  time

Much, much better than naive estimate of  $O(mN^2)$ .

## Newman's Betweenness algorithm:<sup>[4]</sup>



## Newman's Betweenness algorithm:<sup>[4]</sup>

- Set all nodes to have a value  $c_{ij} = 0, j = 1, \dots$  ( $c$  for count).
- Select one node  $i$  and find **shortest paths** to all other  $N - 1$  nodes using breadth-first search.
- Record # equal shortest paths reaching each node.
- Move through nodes according to their distance from  $i$ , starting with the furthest.
- Travel back towards  $i$  from each starting node  $j$ , along shortest path(s), adding 1 to every value of  $c_{i\ell}$  at each node  $\ell$  along the way.
- Whenever more than one possibility exists, apportion according to total number of short paths coming through predecessors.
- Exclude starting node  $j$  and  $i$  from increment.
- Repeat steps 2-8 for every node  $i$  and obtain betweenness as  $B_j = \sum_{i=1}^N c_{ij}$ .

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## Newman's Betweenness algorithm: [4]

- For a **pure tree network**,  $c_{ij}$  is the number of nodes beyond  $j$  from  $i$ 's vantage point.
- Same algorithm for computing drainage area in river networks (with 1 added across the board).
- For **edge betweenness**, use exact same algorithm but now
  - $j$  indexes edges,
  - and we add one to each edge as we traverse it.
- For both algorithms, computation time grows as

$$O(mN).$$

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## Important nodes have important friends:

- So: solve  $\mathbf{A}^T \vec{x} = \lambda \vec{x}$ .
- But which eigenvalue and eigenvector?
- We, the people, would like:
  - A unique solution. ✓
  - $\lambda$  to be real. ✓
  - Entries of  $\vec{x}$  to be real. ✓
  - Entries of  $\vec{x}$  to be non-negative. ✓
  - $\lambda$  to actually mean something ... (maybe too much)
  - Values of  $x_i$  to mean something (what does an observation that  $x_3 = 5x_7$  mean?) (maybe only ordering is informative ...)
  - $\lambda$  to equal 1 would be nice ... (maybe too much)
  - Ordering of  $\vec{x}$  entries to be robust to reasonable modifications of linear assumption (maybe too much)

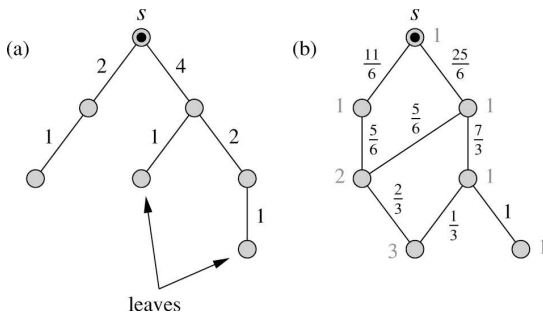
- We rummage around in bag of tricks and pull out the Perron-Frobenius theorem ...

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## Newman's Betweenness algorithm: [4]



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## Perron-Frobenius theorem: If an $N \times N$ matrix $A$ has non-negative entries then:

- $A$  has a real eigenvalue  $\lambda_1 \geq |\lambda_i|$  for  $i = 2, \dots, N$ .
- $\lambda_1$  corresponds to left and right 1-d eigenspaces for which we can choose a basis vector that has non-negative entries.
- The dominant real eigenvalue  $\lambda_1$  is bounded by the minimum and maximum row sums of  $A$ :

$$\min_i \sum_{j=1}^N a_{ij} \leq \lambda_1 \leq \max_i \sum_{j=1}^N a_{ij}$$

- All other eigenvectors have one or more negative entries.
- The matrix  $A$  can make toast.
- Note: Proof is relatively short for symmetric matrices that are strictly positive [6] and just non-negative [3].

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## Important nodes have important friends:

- Define  $x_i$  as the 'importance' of node  $i$ .
- Idea:  $x_i$  depends (somehow) on  $x_j$  if  $j$  is a neighbor of  $i$ .
- Recursive**: importance is transmitted through a network.
- Simplest possibility is a linear combination:

$$x_i \propto \sum_j a_{ji} x_j$$

- Assume further that constant of proportionality,  $c$ , is independent of  $i$ .
- Above gives  $\vec{x} = c \mathbf{A}^T \vec{x}$  or  $\boxed{\mathbf{A}^T \vec{x} = c^{-1} \vec{x} = \lambda \vec{x}}$ .
- Eigenvalue equation based on adjacency matrix ...
- Note: Lots of despair over size of the largest eigenvalue. [7] Lose sight of original assumption's non-physicality.

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## Other Perron-Frobenius aspects:

- Assuming our network is **irreducible**, meaning there is only one component, is reasonable: just consider one component at a time if more than one exists.
- Irreducibility means largest eigenvalue's eigenvector has strictly non-negative entries.
- Analogous to notion of ergodicity: every state is reachable.
- (Another term: **Primitive** graphs and matrices.)

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## Hubs and Authorities

- Generalize eigenvalue centrality to allow nodes to have two attributes:
  - Authority**: how much knowledge, information, etc., held by a node on a topic.
  - Hubness (or Hubosity or Hubbishness or Hubtasticness)**: how well a node 'knows' where to find information on a given topic.
- Original work due to the legendary Jon Kleinberg. <sup>[2]</sup>
- Best hubs point to best authorities.
- Recursive**: Hubs authoritatively link to hubs, authorities hubbishly link to other authorities.
- More**: look for dense links between sets of 'good' hubs pointing to sets of 'good' authorities.
- Known as the **HITS algorithm** (Hyperlink-Induced Topics Search).

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## We can do this:

- $A^T A$  is symmetric.
- $A^T A$  is semi-positive definite so its eigenvalues are all  $\geq 0$ .
- $A^T A$ 's eigenvalues are the square of  $A$ 's singular values.
- $A^T A$ 's eigenvectors form a joyful orthogonal basis.
- Perron-Frobenius tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries.
- So: linear assumption leads to a solvable system.
- What would be very good: find networks where we have independent measures of node 'importance' and see how importance is actually distributed.

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## Hubs and Authorities

- Give each node two scores:
  - $x_i$  = **authority score** for node  $i$
  - $y_i$  = **hubtasticness score** for node  $i$
- As for eigenvector centrality, we connect the scores of neighboring nodes.
- New story I: a good authority is linked to by good hubs.
- Means  $x_i$  should increase as  $\sum_{j=1}^N a_{ji} y_j$  increases.
- Note**: indices are  $ji$  meaning  $j$  has a directed link to  $i$ .
- New story II: good hubs point to good authorities.
- Means  $y_i$  should increase as  $\sum_{j=1}^N a_{ij} x_j$  increases.
- Linearity assumption:

$$\vec{x} \propto A^T \vec{y} \text{ and } \vec{y} \propto A \vec{x}$$

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## Nutshell:

- Measuring centrality is well motivated if hard to carry out well.
- We've only looked at a few major ones.
- Methods are often taken to be more sophisticated than they really are.
- Centrality can be used pragmatically to perform diagnostics on networks (see structure detection).
- Focus on nodes rather than groups or modules is a homo narrativus constraint.
- Possible that better approaches will be developed.

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## Hubs and Authorities

- So let's say we have

$$\vec{x} = c_1 A^T \vec{y} \text{ and } \vec{y} = c_2 A \vec{x}$$

where  $c_1$  and  $c_2$  must be positive.

- Above equations combine to give

$$\vec{x} = c_1 A^T c_2 A \vec{x} = \lambda A^T A \vec{x}$$

where  $\lambda = c_1 c_2 > 0$ .

- It's all good**: we have the heart of singular value decomposition before us ...

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