

# Singular Value Decomposition

## Matrixology (Linear Algebra)—Episode 25/25

### MATH 124, Spring, 2015

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1 of 34

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2 of 34

Outline

The Fundamental Theorem of Linear Algebra

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3 of 34

## Fundamental Theorem of Linear Algebra

- Applies to any  $m \times n$  matrix  $A$ .
- Symmetry of  $A$  and  $A^T$ .

Where  $\vec{x}$  lives:

- Row space  $C(A^T) \subset R^n$ .
- (Right) Nullspace  $N(A) \subset R^n$ .
- $\dim C(A^T) + \dim N(A) = r + (n - r) = n$
- Orthogonality:  $C(A^T) \otimes N(A) = R^n$

Where  $\vec{b}$  lives:

- Column space  $C(A) \subset R^m$ .
- Left Nullspace  $N(A^T) \subset R^m$ .
- $\dim C(A) + \dim N(A^T) = r + (m - r) = m$
- Orthogonality:  $C(A) \otimes N(A^T) = R^m$

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Theorem of  
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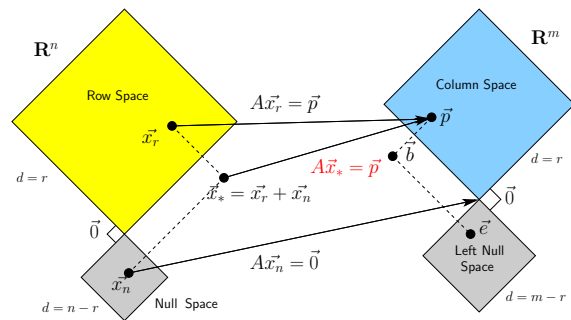
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4 of 34

Best solution  $\vec{x}_*$  when  $\vec{b} = \vec{p} + \vec{e}$ :



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The Fundamental  
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5 of 34

## Fundamental Theorem of Linear Algebra

Now we see:

- Each of the four fundamental subspaces has a 'best' orthonormal basis
- The  $\hat{v}_i$  span  $R^n$
- We find the  $\hat{v}_i$  as eigenvectors of  $A^T A$ .
- The  $\hat{u}_i$  span  $R^m$
- We find the  $\hat{u}_i$  as eigenvectors of  $A A^T$ .

Happy bases

- $\{\hat{v}_1, \dots, \hat{v}_r\}$  span Row space
- $\{\hat{v}_{r+1}, \dots, \hat{v}_n\}$  span Null space
- $\{\hat{u}_1, \dots, \hat{u}_r\}$  span Column space
- $\{\hat{u}_{r+1}, \dots, \hat{u}_m\}$  span Left Null space

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The Fundamental  
Theorem of  
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Hubs and  
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6 of 34

## Fundamental Theorem of Linear Algebra

### How $A\vec{x}$ works:



$$A\hat{v}_i = \sigma_i \hat{u}_i \text{ for } i = 1, \dots, r.$$

and

$$A\hat{v}_i = \vec{0} \text{ for } i = r + 1, \dots, n.$$

### ► Matrix version:

$$A = U\Sigma V^T$$

- $A$  sends each  $\hat{v}_i \in C(A^T)$  to its partner  $\hat{u}_i \in C(A)$  with a positive stretch/shrink factor  $\sigma_i > 0$ .
- $A$  is diagonal with respect to these bases.
- When viewed in the right way, every  $A$  is a diagonal matrix  $\Sigma$ .

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The Fundamental  
Theorem of  
Linear Algebra  
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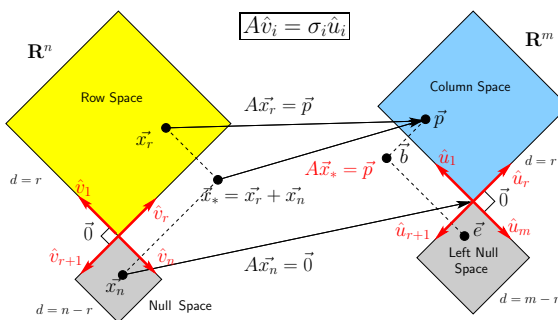
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7 of 34

## The complete big picture:



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8 of 34

## Hubs and Authorities

- Idea: allow nodes in a knowledge network to have two attributes:
  1. **Authority**: how much knowledge, information, etc., held by a node on a topic.
  2. **Hubness (or Hubosity or Hubbishness or Hubtasticness)**: how well a node 'knows' where to find information on a given topic.
- Original work due to the legendary Jon Kleinberg.
- Best hubs point to best authorities.
- **Recursive**: Hubs authoritatively link to hubs, authorities hubbishly link to other authorities.
- **More**: look for dense links between sets of 'good' hubs pointing to sets of 'good' authorities.
- Known as the **HITS algorithm** (Hyperlink-Induced Topics Search).

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Theorem of  
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9 of 34

## Hubs and Authorities

- Give each node two scores:
  1.  $x_i$  = **authority score** for node  $i$
  2.  $y_i$  = **hubtasticness score** for node  $i$
- We connect the scores of neighboring nodes.
- I: a good authority is linked to by good hubs.
- Means  $x_i$  should **increase** as  $\sum_{j=1}^N a_{ji} y_j$  increases.
- **Note**: indices are  $ji$  meaning  $j$  has a directed link to  $i$ .
- II: good hubs point to good authorities.
- Means  $y_i$  should **increase** as  $\sum_{j=1}^N a_{ij} x_j$  increases.
- Linearity assumption:

$$\vec{x} \propto A^T \vec{y} \text{ and } \vec{y} \propto A \vec{x}$$

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10 of 34

## Hubs and Authorities

- So let's say we have

$$\vec{x} = c_1 A^T \vec{y} \text{ and } \vec{y} = c_2 A \vec{x}$$

where  $c_1$  and  $c_2$  must be positive.

- Above equations combine to give

$$\vec{x} = c_1 A^T c_2 A \vec{x} = \lambda A^T A \vec{x}.$$

where  $\lambda = c_1 c_2 > 0$ .

- **It's all good**: we have the heart of singular value decomposition before us...

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11 of 34

## We can do this:

- $A^T A$  is symmetric.
- $A^T A$  is semi-positive definite so its eigenvalues are all  $\geq 0$ .
- $A^T A$ 's eigenvalues are the square of  $A$ 's singular values.
- $A^T A$ 's eigenvectors form a joyful orthogonal basis.
- The splendid **Perron-Frobenius theorem** tells us that only the dominant eigenvalue's eigenvector can be chosen to have non-negative entries.
- So: linear assumption leads to a solvable system.
- What would be very good: find networks where we have independent measures of node 'importance' and see how importance is actually distributed.

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12 of 34

## Image approximation (80x60)

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### Idea: use SVD to approximate images

- ▶ Interpret elements of matrix  $A$  as color values of an image.
- ▶ Truncate series SVD representation of  $A$ :

$$A = U\Sigma V^T = \sum_{i=1}^r \sigma_i \hat{u}_i \hat{v}_i^T$$

- ▶ Use fact that  $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$ .
- ▶ Rank  $r \leq \min(m, n)$ .
- ▶ Rank  $r \leq \#$  of pixels on shortest side.
- ▶ For color: approximate 3 matrices (RGB).

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