



**122 Matrixology (Linear Algebra)—Practice exam #4**  
**University of Vermont, Fall Semester,**

Name: \_\_\_\_\_

- Total points: 36 (3 points per question); Time allowed: 165 minutes. Smile.
  - Current brains only: No pensieves, calculators, or similar gadgets allowed.
  - For full points, *please show all working clearly*.
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1. Draw the 'big picture' of how  $\mathbf{A}\vec{x} = \vec{b}$  works when  $\mathbf{A}$  is an  $m \times n$  matrix. Indicate on your diagram the following:
  - (a) Which space is  $R^m$  and which is  $R^n$ .
  - (b) Row space, column space, nullspace, and left nullspace.
  - (c) The dimensions of the above subspaces in terms of  $r$ ,  $m$ , and  $n$ .
  - (d) How  $\mathbf{A}$  maps vectors.
  - (e) Where the vectors  $\vec{x} = \vec{x}_r + \vec{x}_n$  and  $\vec{b} = \vec{p} + \vec{e}$  live.
  - (f) The appropriate orthogonality of subspaces.

2. For the four general cases of  $\mathbf{A}\vec{x} = \vec{b}$  below:

- (a) give an example reduced row echelon form matrix  $\mathbf{R}_A$ ;
- (b) sketch the appropriate cartoon abstract 'big pictures';
- (c) indicate the number of possible solutions (0, 1, or  $\infty$ );
- (d) and note whether or not nullspace and left nullspace are equal to  $\{\vec{0}\}$  (Y/N).

| case                | example $\mathbf{R}_A$ | big picture | # solutions | $N(\mathbf{A}) = \{\vec{0}\}$ ? | $N(\mathbf{A}^T) = \{\vec{0}\}$ ? |
|---------------------|------------------------|-------------|-------------|---------------------------------|-----------------------------------|
| $m = r$<br>$n = r$  |                        |             |             |                                 |                                   |
| $m = r,$<br>$n > r$ |                        |             |             |                                 |                                   |
| $m > r,$<br>$n = r$ |                        |             |             |                                 |                                   |
| $m > r,$<br>$n > r$ |                        |             |             |                                 |                                   |

3. Given a matrix  $\mathbf{A}$  and its transpose  $\mathbf{A}^T$  have the following reduced row echelon forms, respectively,

$$\mathbf{R}_{\mathbf{A}} = \begin{bmatrix} 1 & 2 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \text{ and } \mathbf{R}_{\mathbf{A}^T} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

answer the following questions.

- (a)  $m = \underline{\hspace{2cm}}$ ,  $n = \underline{\hspace{2cm}}$ ,  $r = \underline{\hspace{2cm}}$ ,  
 $\dim C(\mathbf{A}^T) = \underline{\hspace{2cm}}$ ,  $\dim C(\mathbf{A}) = \underline{\hspace{2cm}}$ ,  
 $\dim N(\mathbf{A}) = \underline{\hspace{2cm}}$ ,  $\dim N(\mathbf{A}^T) = \underline{\hspace{2cm}}$ .
- (b) Find bases for  $\mathbf{A}$ 's row space and column space.

- (c) Find a basis for  $\mathbf{A}$ 's nullspace

4. LU decomposition:

Find  $\mathbf{U}$  for the following matrix

$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 2 \\ 4 & 1 & 4 \\ -4 & 11 & 0 \end{bmatrix}.$$

Write down each row operation, the multipliers  $l_{21}$ ,  $l_{31}$ , and  $l_{32}$ , and the corresponding elimination matrices  $\mathbf{E}_{21}$ ,  $\mathbf{E}_{31}$ , and  $\mathbf{E}_{32}$ .

5. This question carries on with the the preceding question's  $\mathbf{A}$ .

(a) What are the pivots of  $\mathbf{A}$ ?

(b) Write down a general formula for  $|\mathbf{A}|$  in terms of its pivots (remembering that in general, row swaps may be needed to reduce  $\mathbf{A}$  to  $\mathbf{U}$ ), and compute the determinant of the  $\mathbf{A}$  we have here.

(c) Write down the inverses of the elimination matrices and compute

$$\mathbf{L} = \mathbf{E}_{21}^{-1} \mathbf{E}_{31}^{-1} \mathbf{E}_{32}^{-1}.$$

6. Least squares approximation:

(a) Given

$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad \vec{b} = \begin{bmatrix} 7 \\ -1 \\ 3 \end{bmatrix},$$

solve the normal equation  $\mathbf{A}^T \mathbf{A} \vec{x}^* = \mathbf{A}^T \vec{b}$ .

(b) Find  $\vec{p}$  and  $\vec{e}$ , the components of  $\vec{b}$  that live in column space and left nullspace respectively.

7. The Gram-Schmidt process:

Consider the subspace  $\mathbf{S}$  of  $R^3$  that is spanned by the following two linearly independent vectors:

$$\vec{a}_1 = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}, \quad \text{and} \quad \vec{a}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}.$$

Find an orthonormal basis vectors ( $\hat{q}_1$  and  $\hat{q}_2$ ) for  $\mathbf{S}$  using the (exciting) Gram-Schmidt process.

(b) Consequently, for the matrix  $\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 2 & 1 \end{bmatrix}$  find the factorization  $\mathbf{A} = \mathbf{QR}$   
(i.e., find  $\mathbf{Q}$  and  $\mathbf{R}$ ).



8. (a) Find the eigenvalues and eigenvectors of the following matrix:

$$\mathbf{A} = \begin{bmatrix} 3 & 0 \\ 3 & 1 \end{bmatrix}$$

- (b) Write down  $\mathbf{A}$ 's diagonalized counterpart  $\mathbf{\Lambda}$  and the transformation matrices  $\mathbf{S}$  and  $\mathbf{S}^{-1}$ .

- (c) Hence determine  $\mathbf{A}^n$  where  $n$  is arbitrary.

9. Computing determinants: Given

$$\mathbf{A} = \begin{bmatrix} 4 & 2 & 0 \\ 4 & 4 & 2 \\ 2 & 2 & 3 \end{bmatrix},$$

(a) Write down the minor matrices  $\mathbf{M}_{12}$ ,  $\mathbf{M}_{22}$ , and  $\mathbf{M}_{32}$ , compute the cofactors  $C_{12}$ ,  $C_{22}$ , and  $C_{32}$ , and hence find  $\det(\mathbf{A})$ .

(b) Also find  $|\mathbf{A}|$  by reducing  $\mathbf{A}$  to an upper triangular matrix with 1's on the leading diagonal.

10. Positive Definite Matrices

Let  $f(x_1, x_2, x_3) = 2x_1^2 + x_2^2 + 6x_3^2 + 2x_1x_2 - 4x_1x_3 + 4x_2x_3$ .

(a) Rewrite  $f(x_1, x_2, x_3)$  as  $\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \mathbf{A} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$  where  $\mathbf{A}$  is a symmetric matrix.

(b) Determine the signs of eigenvalues by finding the pivots.

(c) Write down the definition of positive definiteness. Is this matrix positive definite?

## 11. Singular Value Decomposition

(a) Consider the matrix:

$$\mathbf{A} = \frac{1}{5} \begin{bmatrix} 9 & 12 \\ 8 & -6 \end{bmatrix}.$$

Determine the singular value decomposition of  $\mathbf{A}$ , i.e., find the three matrices  $\mathbf{U}$ ,  $\mathbf{\Sigma}$ , and  $\mathbf{V}^T$  such that  $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$ .

(Reminder:  $\mathbf{A}\hat{v}_i = \sigma_i\hat{u}_i$  and  $\mathbf{A}^T\mathbf{A}\hat{v}_i = \sigma_i^2\hat{v}_i$ .)

- (b) The Big Picture: Illustrate how  $\mathbf{A}$  maps between the happy basis vectors that are the  $\hat{v}_i$ 's and  $\hat{u}_i$ 's. (Please draw the particular Big Picture not the abstract Big picture.)

Complete your picture by adding a unit circle in row space and the ellipse that  $\mathbf{A}$  creates in column space by transforming this circle.

12. (a) True or False (2 pts):

- i. The nullspace of a nontrivial  $1 \times 3$  matrix  $\mathbf{A}$  is a 2-D plane in  $\mathbb{R}^3$ :  
\_\_\_\_\_.
- ii. The product  $\mathbf{A}^T\mathbf{A}$  is symmetric for any  $n \times n$  matrix  $\mathbf{A}$ : \_\_\_\_\_.
- iii. An  $n \times n$  matrix cannot be diagonalized if one or more eigenvalues of  $\mathbf{A}$  are 0: \_\_\_\_\_.
- iv. The matrix  $\mathbf{M} = [\vec{v}_1 | \vec{v}_2]$  transforms a vector's representation from the basis  $\{\vec{v}_1, \vec{v}_2\}$  to the natural basis: \_\_\_\_\_.
- v. The determinant of a matrix  $\mathbf{A}$  is equal to the sum of  $\mathbf{A}$ 's eigenvalues:  
\_\_\_\_\_.
- vi. The matrices  $\mathbf{A}$  and  $\mathbf{A}^T$  have different eigenvalues: \_\_\_\_\_.

(b) Find the determinant of the following matrix (1 pt):

$$\mathbf{A}_n = \begin{bmatrix} \cos(1) & \cos(2) & \cdots & \cos(n) \\ \cos(n+1) & \cos(n+2) & \cdots & \cos(2n) \\ \vdots & \vdots & \ddots & \vdots \\ \cos(n(n-1)+1) & \cos(n(n-1)+2) & \cdots & \cos(n^2) \end{bmatrix}$$

## **The Triumphant Bonus Page:**