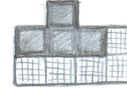


**MATH 124: Matrixology (Linear Algebra)**  
**Level Tetris (1984) ↗, 10 of 10**  
**University of Vermont, Spring 2015**



**Dispersed:** Wednesday, April 22, 2015.

**Due:** By start of lecture, Thursday, April 30, 2015.

**Sections covered:** 6.5, 6.7.

*Some useful reminders:*

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**Office hours:** 12:30 to 3:00 pm Mondays

**Course website:** <http://www.uvm.edu/~pdodds/teaching/courses/2015-01UVM-124>

**Textbook:** "Introduction to Linear Algebra" (3rd or 4th edition) by Gilbert Strang (published by Wellesley-Cambridge Press).

- All questions are worth 3 points unless marked otherwise.
- Please use a cover sheet and write your name on the back and the front of your assignment.
- You must show all your work clearly.
- You may use Matlab to check your answers for non-Matlab questions (usually Qs. 1–8).
- Please list the names of other students with whom you collaborated.

**Reminder:** This assignment cannot be dropped.

1. (Q 4, 6.5) Show that the function  $f(x_1, x_2) = x_1^2 + 4x_1x_2 + 3x_2^2$  does not have a minimum at  $(0, 0)$  even though it has positive coefficients.

Do this by rewriting  $f(x_1, x_2)$  as  $\begin{bmatrix} x_1 & x_2 \end{bmatrix} \mathbf{A} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  and finding the pivots of  $\mathbf{A}$  and noting their signs (and explaining why the signs of the pivots matter).

Write  $f$  as a difference of squares and find a point  $(x_1, x_2)$  where  $f$  is negative.

Note of caution: All of this signs matching for pivots and eigenvalues falls apart if we have to do row swaps in our reduction.

2. (Q 9, 6.5) Find the 3 by 3 matrix  $\mathbf{A}$  and its pivots, rank, eigenvalues, and determinant:

$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} \mathbf{A} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 4(x_1 - x_2 + 2x_3)^2.$$

Is this matrix positive definite, semi-positive definite, or neither?

3. (following set of questions based on Q 7, Section 6.7)

Singular Value Decomposition = Happiness.

Consider

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}.$$

- What are  $m$ ,  $n$ , and  $r$  for this matrix?
  - What are the dimensions of  $\mathbf{U}$ ,  $\mathbf{\Sigma}$ , and  $\mathbf{V}$ ?
  - Calculate  $\mathbf{A}^T\mathbf{A}$  and  $\mathbf{A}\mathbf{A}^T$ .
4. For the matrix  $\mathbf{A}$  given above, find the eigenvalues and eigenvectors of  $\mathbf{A}^T\mathbf{A}$ , and thereby construct  $\mathbf{V}$  and  $\mathbf{\Sigma}$ .

See this tweet for some post-it based help:

<https://twitter.com/matrixologyvox/status/593540446845947904>

5. For the same  $\mathbf{A}$ , now find the basis  $\{\hat{u}_i\}$  using the essential connection  $\mathbf{A}\hat{v}_i = \sigma_i\hat{u}_i$ .

Construct  $\mathbf{U}$  from the basis you find.

Again see this tweet for some post-it based help:

<https://twitter.com/matrixologyvox/status/593540446845947904>

6. Next find the  $\{\hat{u}_i\}$  in a different way by finding the eigenvalues and eigenvectors of  $\mathbf{A}\mathbf{A}^T$ .
- Put everything together and show that  $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$ .
  - Draw the 'big picture' for this  $\mathbf{A}$  showing which  $\hat{v}_i$ 's are mapped to which  $\hat{u}_i$ 's.
  - Which basis vectors, if any, belong to the two nullspaces?

8. Finally, for this same  $\mathbf{A}$ , perform the following calculation:

$$\sigma_1\hat{u}_1\hat{v}_1^T + \sigma_2\hat{u}_2\hat{v}_2^T + \dots + \sigma_r\hat{u}_r\hat{v}_r^T$$

where  $r$  is the rank of  $\mathbf{A}$ .

You should obtain  $\mathbf{A}$ ...

9. Matlab question.

Verify the signs you found for the pivots of  $\mathbf{A}$  in question 1 by using Matlab to find  $\mathbf{A}$ 's eigenvalues.

10. Matlab question.

Use Matlab to compute the SVD for the matrix  $\mathbf{A}$  you explored in questions 3–8.

11. (The bonus one pointer)

Where does the fearsome kiwi rank among among rattites and what's unusual about the kiwi egg?