Chapter 2: Lecture 1 Linear Algebra, Course 124C, Spring, 2009

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Admin:

Paper products:

- 1. Outline
- 2. "The Fundamental Theorem of Linear Algebra" [1]
- 3. "Too Much Calculus" ^[2]

Office hours:

Tuesday: 2:30 pm to 4:30 pm Thursday: 11:30 am to 12:30 pm Rm 203, Math Building



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Basics:

Instructor: Prof. Peter Dodds

Lecture room and meeting times: 367 Votey, Tuesday and Thursday, 1:00 pm to 2:15 pm

- Office: 203 Lord House, 16 Colchester Avenue
- E-mail: pdodds@uvm.edu
- Course website: http://www.uvm.edu/~pdodds/teaching/ courses/2009-01UVM-124/
- Textbook: "Introduction to Linear Algebra" (3rd ed.) by Gilbert Strang; Wellesley-Cambridge Press.

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Grading breakdown:

1. Assignments (40%)

- Ten one-week assignments.
- Lowest assignment score will be dropped.
- The last assignment cannot be dropped!
- Each assignment will have a random bonus point question which has nothing to do with linear algebra.

2. Midterm exams (35%)

- Three 75 minutes tests distributed throughout the course, all of equal weighting.
- 3. Final exam (24%)
 - Three hours of pure happiness.
 - May 4, 8:00 am to 11:00 am; held in normal lecture room.

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Grading breakdown:

- Homework (0%)—Problems assigned online from the textbook. Doing these exercises will be most beneficial and will increase happiness.
- 2. General attendance (1%)—it is extremely desirable that students attend class, and class presence will be taken into account if a grade is borderline.

Schedule:

The course will mainly cover chapters 2 through 6 of the textbook. (You should know all about Chapter 1.)

			Importance
Week # (dates)	Tuesday	Thursday	Usages
1 (1/13 and 1/15)	Lecture	Lecture + A 1	Key problen
2 (1/20 and 1/22)	Lecture	Lecture + A 2	Three ways
3 (1/27 and 1/29)	Lecture	Lecture + A 3	looking
4 (2/3 and 2/5)	Lecture	Test 1	Colbert on
5 (2/10 and 2/12)	Lecture	Lecture + A 4	Equations
6 (2/17 and 2/19)	Lecture	Lecture + A 5	References
7 (2/24 and 2/26)	Lecture	Lecture + A 6	
8 (3/3 and 3/5)	Town Recess	Lecture	
9 (3/10 and 3/12)	Spring recess	Spring recess	
10 (3/17 and 3/19)	Test 2	Lecture + A 7	
11 (3/24 and 3/26)	Lecture	Lecture + A 8	
12 (3/31 and 4/2)	Lecture	Lecture + A 9	
13 (4/7 and 4/9)	Lecture	Test 3	
13 (4/14 and 4/16)	Lecture	Lecture + A 10	
14 (4/21 and 4/23)	Lecture	Lecture	Frame 7/29
15 (4/28)	Lecture	—	- ヨ ー りゅ

How grading works:

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Questions are worth 3 points according to the following scale:

- ► 3 = correct or very nearly so.
- 2 = acceptable but needs some revisions.
- 1 = needs major revisions.
- ▶ 0 = way off.

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Usages

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Important dates:

- 1. Classes run from Monday, January 12 to Wednesday, April 29.
- 2. Add/Drop, Audit, Pass/No Pass deadline—Monday, January 26.
- 3. Last day to withdraw—Friday, March 30.
- 4. Reading and exam period—Thursday, April 30th to Friday, May 8.

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More stuff:

Do check your zoo account for updates regarding the course.

Academic assistance: Anyone who requires assistance in any way (as per the ACCESS program or due to athletic endeavors), please see or contact me as soon as possible.

More stuff:

Late policy: Unless in the case of an emergency (a real one) or if an absence has been predeclared and a make-up version sorted out, assignments that are not turned in on time or tests that are not attended will be given 0%.

Computing: Students are encouraged to use Matlab or something similar to check their work.

Note: for assignment problems, written details of calculations will be required.

More stuff:

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Being good people:

- 1. In class there will be no electronic gadgetry, no cell phones, no beeping, no text messaging, etc. You really just need your brain, some paper, and a writing implement here (okay, and Matlab or similar).
- 2. Second, I encourage you to email me questions, ideas, comments, etc., about the class but request that you please do so in a respectful fashion.
- 3. Finally, as in all UVM classes, Academic honesty will be expected and departures will be dealt with appropriately. See http://www.uvm.edu/cses/ for guidelines.

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Grading:	Ch. 2: Lec.
A 93–96 B 83–86 C 73–76	D+ 67–69 Colbert on Equations D- 60–62 References

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Outline

Why are we doing this?

Linear Algebra is

a body of mathematics that deals with discrete problems.

Many things are discrete:

- Information (0's & 1's, letters, words)
- People (sociology)
- Networks (the Web, people again, food webs, ...)
- Sounds (musical notes)

Even more:

If real data is continuous, we almost always discretize it (0's and 1's)

Matrices as gadgets:

A transforms \vec{x} into \vec{x}' through multiplication

 $\vec{x}' = A\vec{x}$

Can use matrices to:

- Grow vectors
- Shrink vectors
- Rotate vectors
- Flip vectors
- Do all these things to different directions



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Why are we doing this?

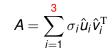
Linear Algebra is used in many fields to solve problems:

- Engineering
- Computer Science (Google's Pagerank)
- Physics
- Economics
- Biology
- Ecology
- ...

Linear Algebra is as important as calculus.

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Image approximation (80x60)





Outline Importance

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Three key problems of Linear Algebra

1. Given a matrix A and a vector \vec{b} , find \vec{x} such that

 $A\vec{x} = \vec{b}.$

2. Eigenvalue problem: Given A, find λ and \vec{v} such that

 $\mathbf{A}\vec{\mathbf{v}}=\lambda\vec{\mathbf{v}}.$

3. Coupled linear differential equations:

$$\frac{\mathrm{d}}{\mathrm{d}t}y(t) = \mathbf{A}y(t)$$

Our focus will be largely on #1, partly on #2.

Our friend $A\vec{x} = \vec{b}$

Broadly speaking, $A\vec{x} = \vec{b}$ translates as follows:

- *b* represents reality (e.g., music, structure)
- ► A contains building blocks (e.g., notes, shapes)
- \vec{x} specifies how we combine our building blocks to represent \vec{b} .

How can we disentangle an orchestra's sound?

What about pictures, waves, signals, ...?

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Key problems

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Key problems

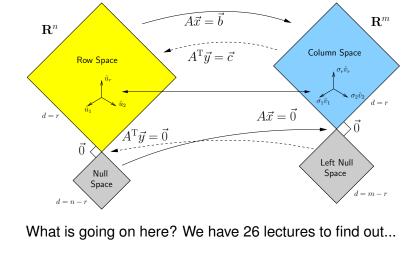
Equations

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To deeply understand the equation $A\vec{x} = \vec{b}$, the Fundamental Theorem of Linear Algebra, and the following picture:



Our friend $A\vec{x} = \vec{b}$

What does knowing \vec{x} give us?

If we can represent reality as a superposition (or combination) of simple elements, we can do many things:

- Compress information
- See how we can alter information
- Find a system's simplest representation
- Find a system's most important elements
- See how to adjust a system in a principled defined way

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References

Three ways to understand $A\vec{x} = \vec{b}$:

- ► Way 1: The Row Picture
- Way 2: The Column Picture
- Way 3: The Matrix Picture

Example:

- Call this a 2 by 2 system of equations.
- 2 equations with 2 unknowns.
- Standard method of solving by adding and subtracting multiples of equations from each other
 Row Picture

Three ways to understand $A\vec{x} = \vec{b}$:

The column picture:

See

as

General problem

$$x_1\vec{a}_1+x_2\vec{a}_2=\vec{b}$$

 $x_1 \begin{bmatrix} -1 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}.$

- Column vectors are 'building blocks'
- Key idea: try to 'reach' \vec{b} by combining multiples of column vectors \vec{a}_1 and \vec{a}_2 .

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Ch. 2: Lec. 1

Three ways to understand $A\vec{x} = \vec{b}$:

Row Picture—what we are doing:

- (a) Finding intersection of two lines
- (b) Finding the values of x₁ and x₂ for which both equations are satisfied (true/happy)
- A splendid and deep connection:
 (a) Geometry = (b) Algebra

Three possible kinds of solution:

- 1. Lines intersect at one point —One, unique solution
- 2. Lines are parallel and disjoint -No solutions
- 3. Lines are the same —Infinitely many solutions

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Three ways to understand $A\vec{x} = \vec{b}$:

We love the column picture:

- Intuitive.
- Generalizes easily to many dimensions.

Three possible kinds of solution:

- 1. $\vec{a}_1 \parallel \vec{a}_2$: 1 solution
- 2. $\vec{a}_1 \parallel \vec{a}_2 \not\parallel \vec{b}$: No solutions
- 3. $\vec{a}_1 \parallel \vec{a}_2 \parallel \vec{b}$: infinitely many solutions

Assuming neither \vec{a}_1 or \vec{a}_1 are $\vec{0}$.

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Three ways of looking...

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Three ways to understand $A\vec{x} = \vec{b}$:

Difficulties:

- Do we give up if $A\vec{x} = \vec{b}$ has no solution?
- **No!** We can still find the \vec{x} that gets us as close to \vec{b} as possible.
- Method of approximation—very important!
- We may not have the right building blocks but we can do our best.

The Matrix Picture

Key idea in linear algebra:

- Decomposition (or factorization) of matrices.
- Matrices can often be written as products or sums of simpler matrices
- $A = LU, A = QR, A = U\Sigma V^{T}, A = \sum_{i} \lambda_{i} \vec{v} \vec{v}^{T}, \dots$

Three ways to understand $A\vec{x} = \vec{b}$:

 $x_1 \begin{bmatrix} -1 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}.$

The Matrix Picture:



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$A\vec{x} = \vec{b} : \begin{bmatrix} -1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$

A is now an operator:

- A transforms \vec{x} into \vec{b} .
- In general, A does two things to \vec{x} :
 - 1. Rotation
 - 2. Dilation (stretching/contraction)



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The truth about mathematics

The Colbert Report on Math (February 7, 2006)

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References I

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The fundamental theorem of linear algebra. *The American Mathematical Monthly*, 100(9):848–855, 1993. pdf (⊞)

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Too much calculus, 2002.

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